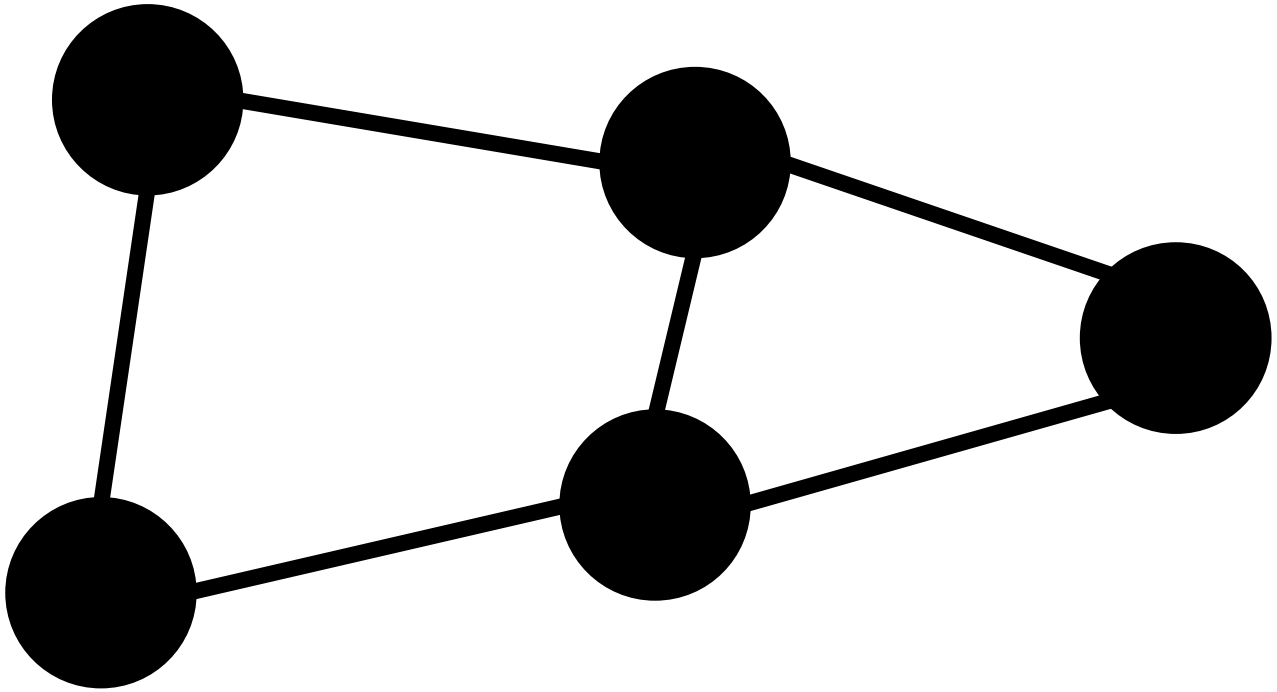
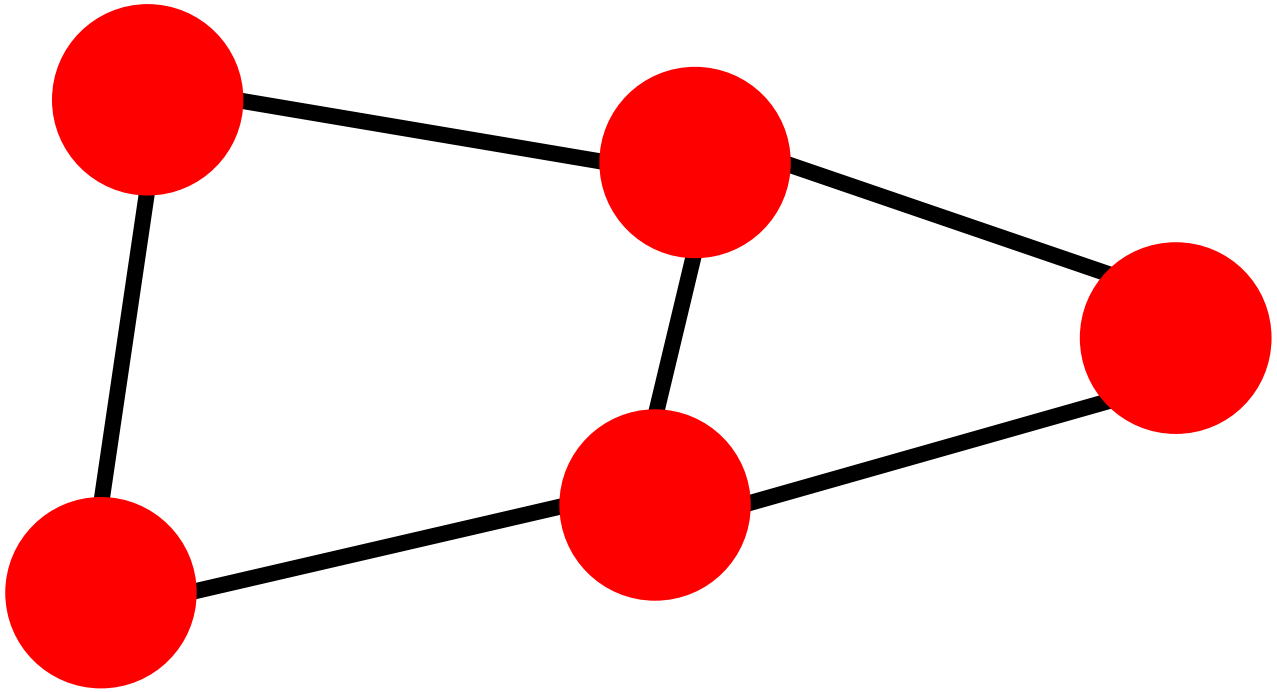
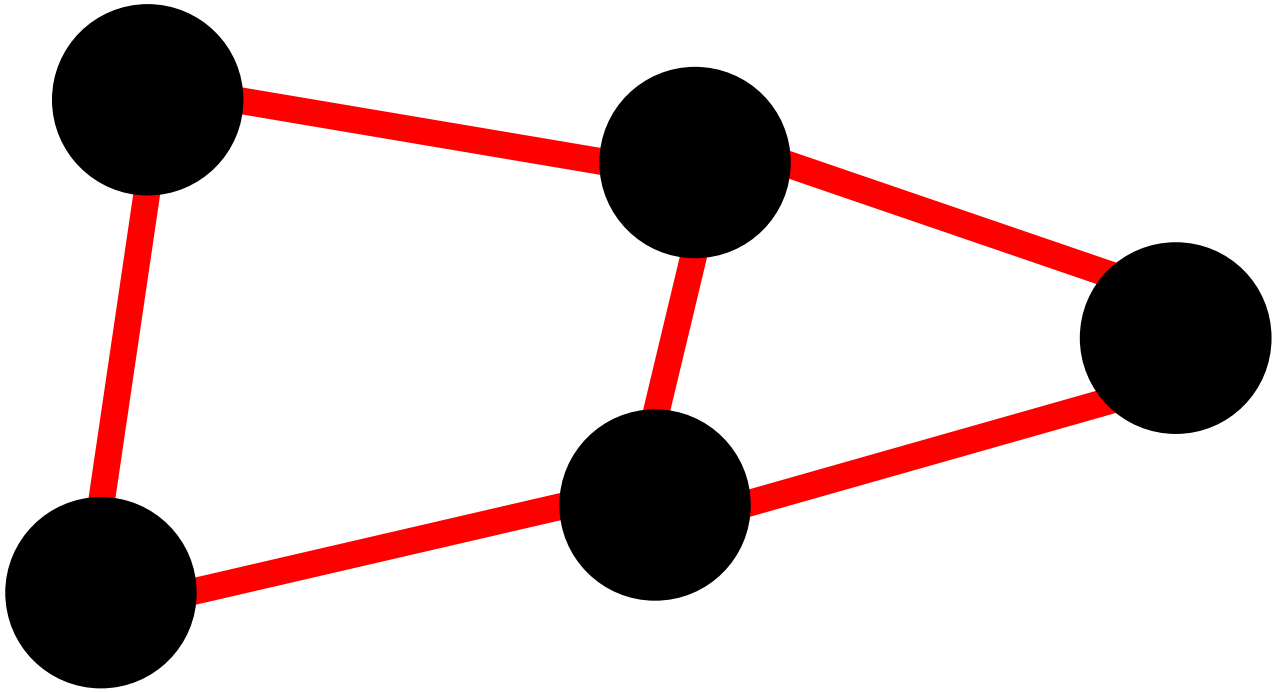
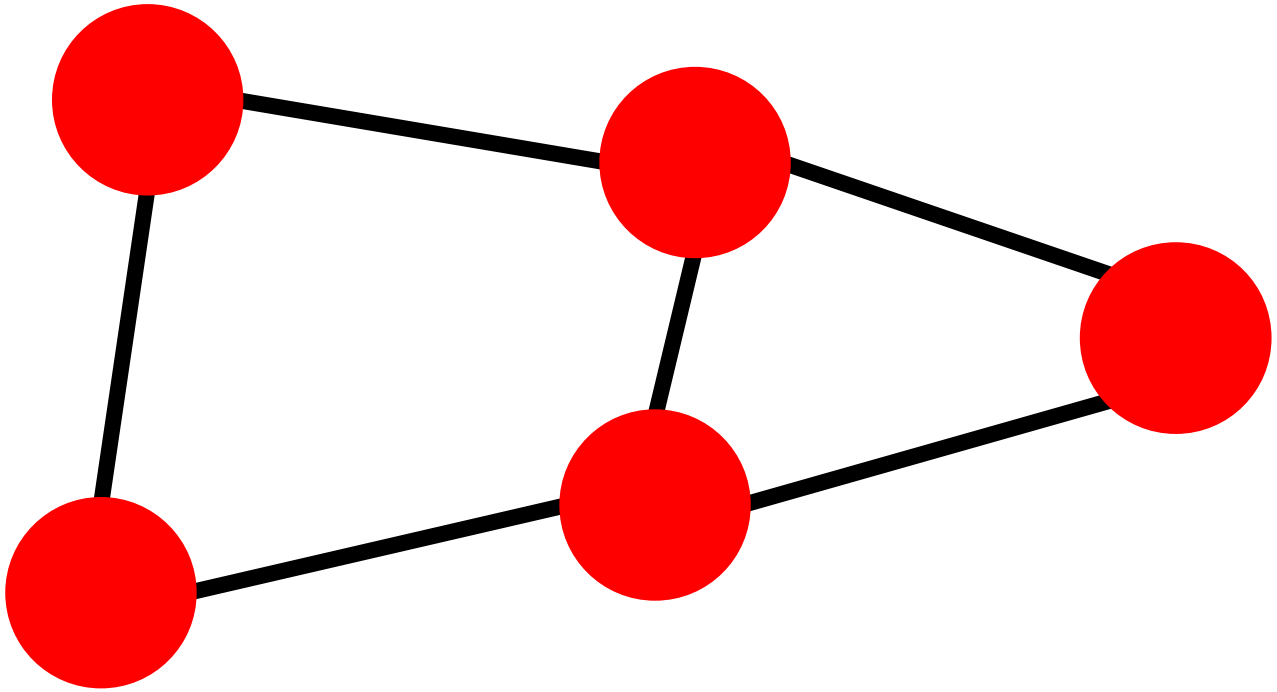
Graphentheorie
und
Routenplanung

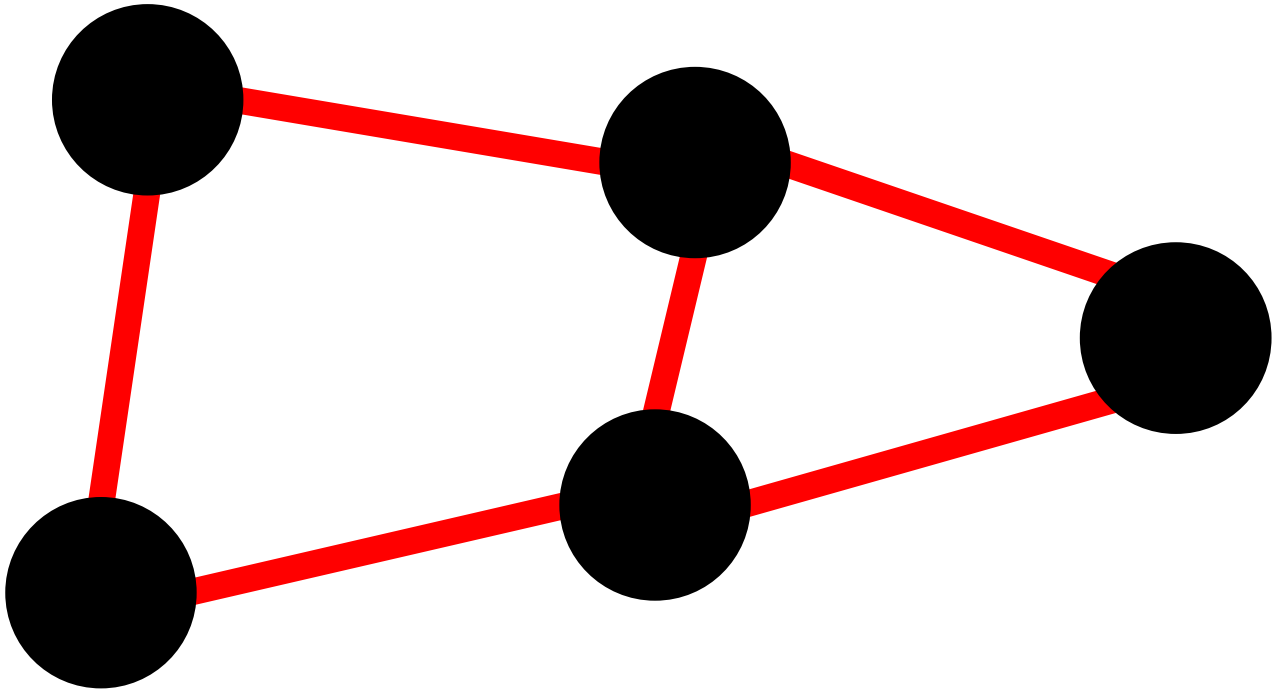
Graphen

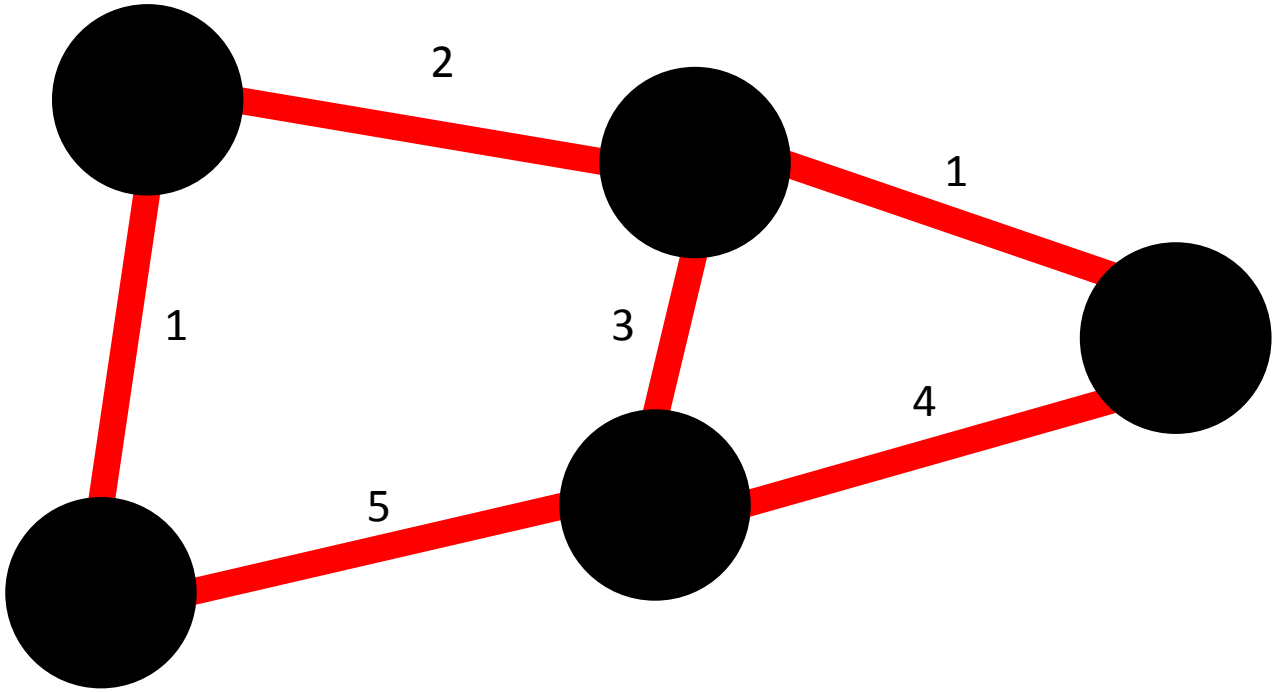




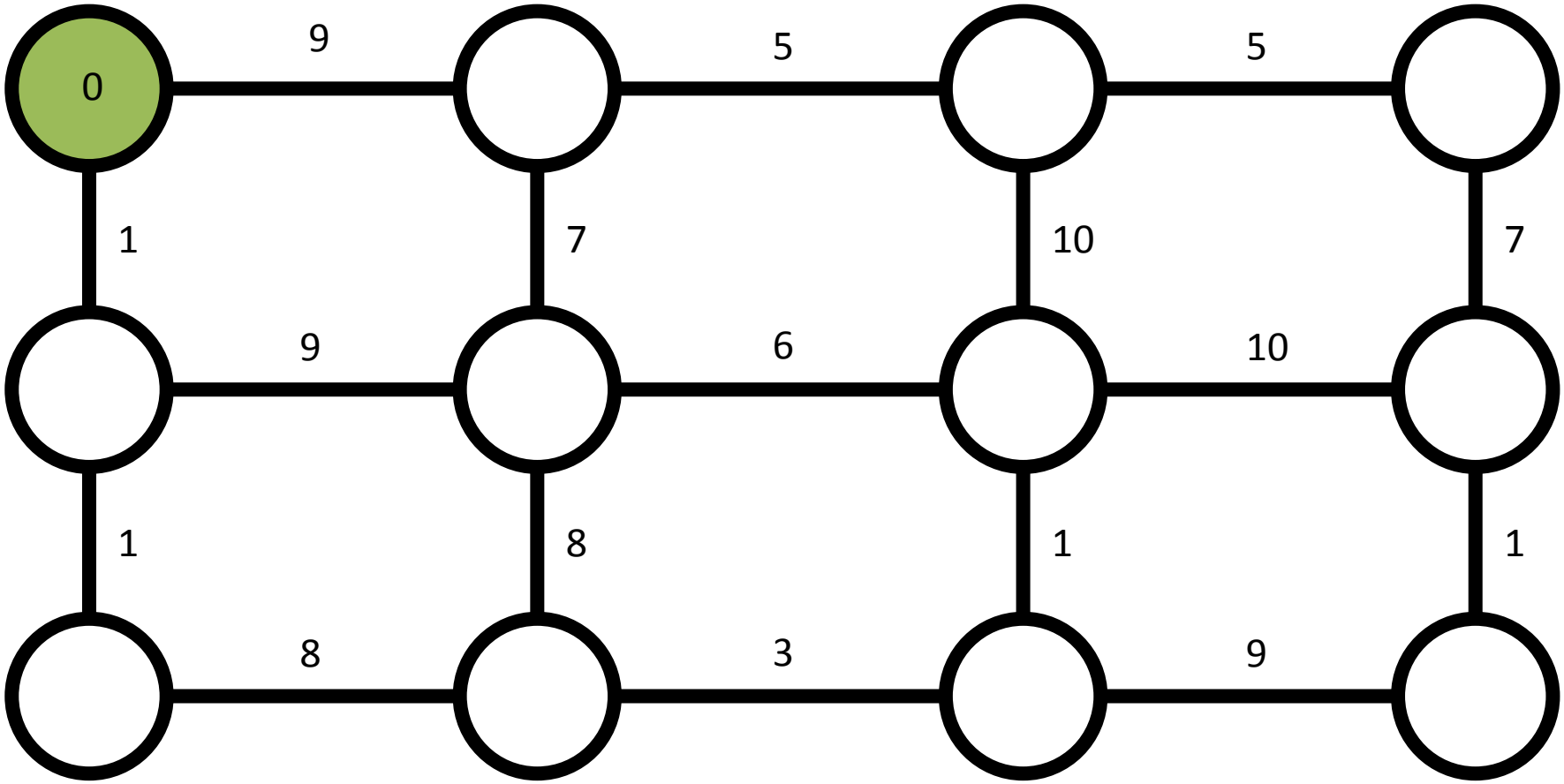


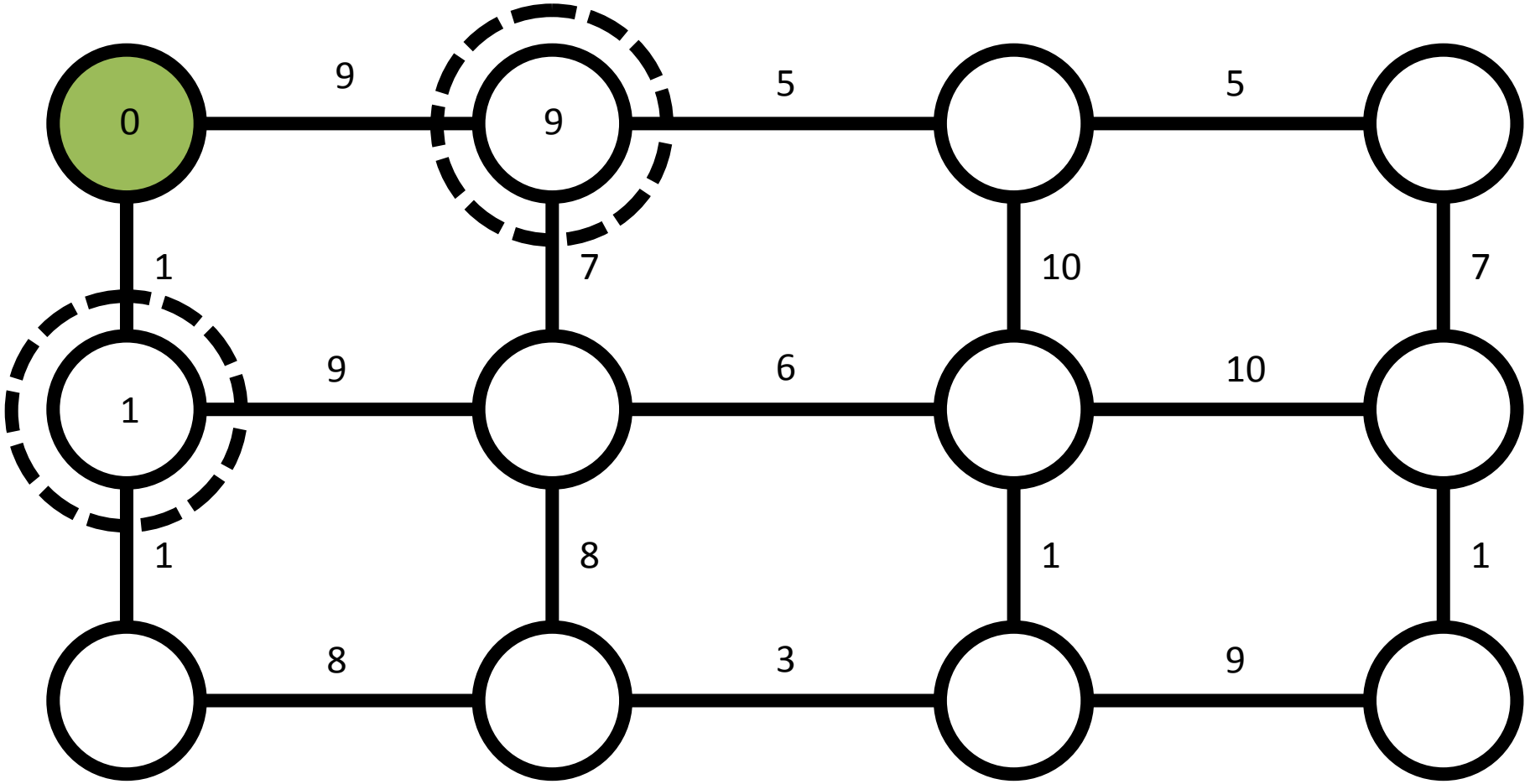


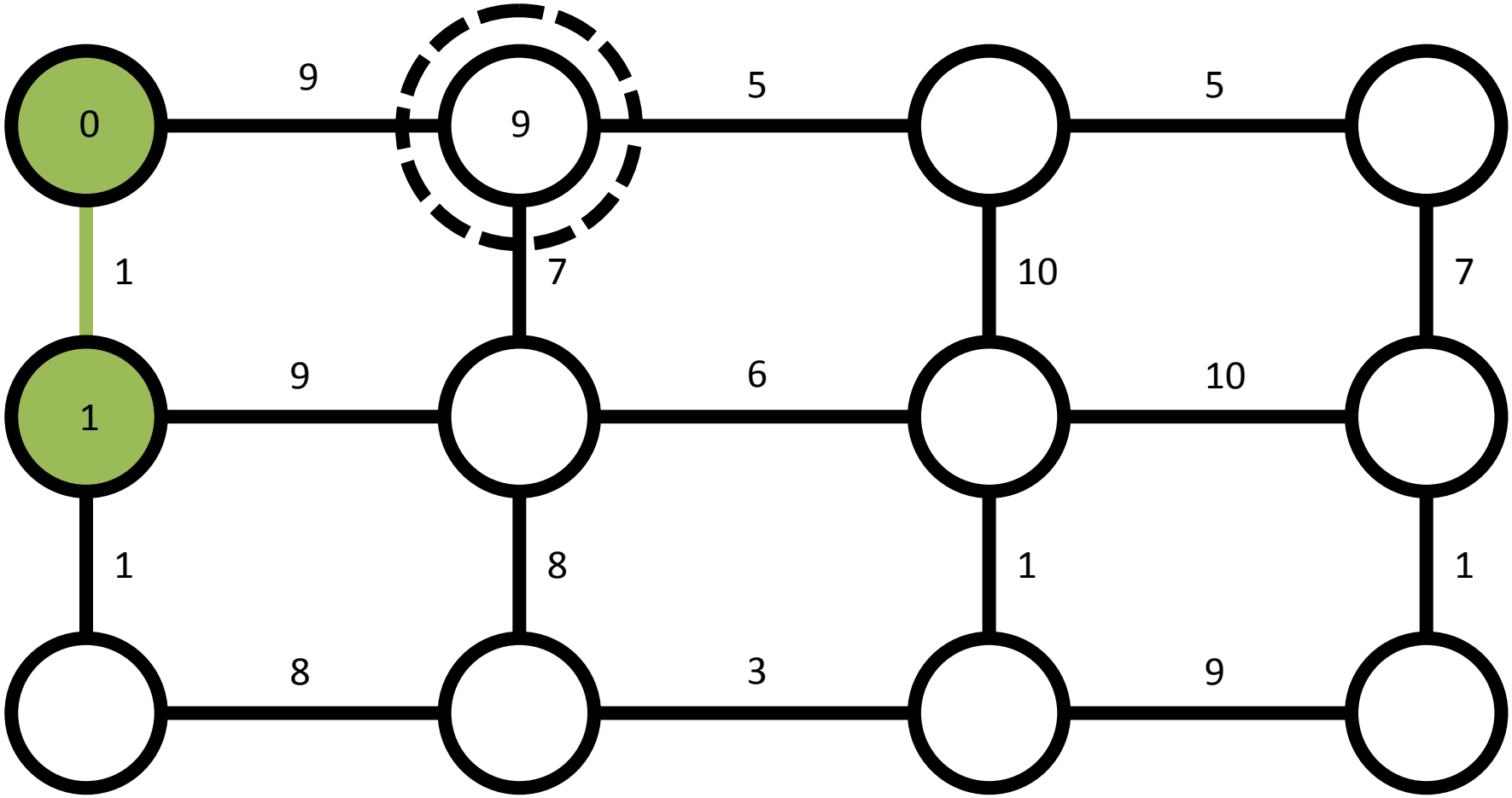


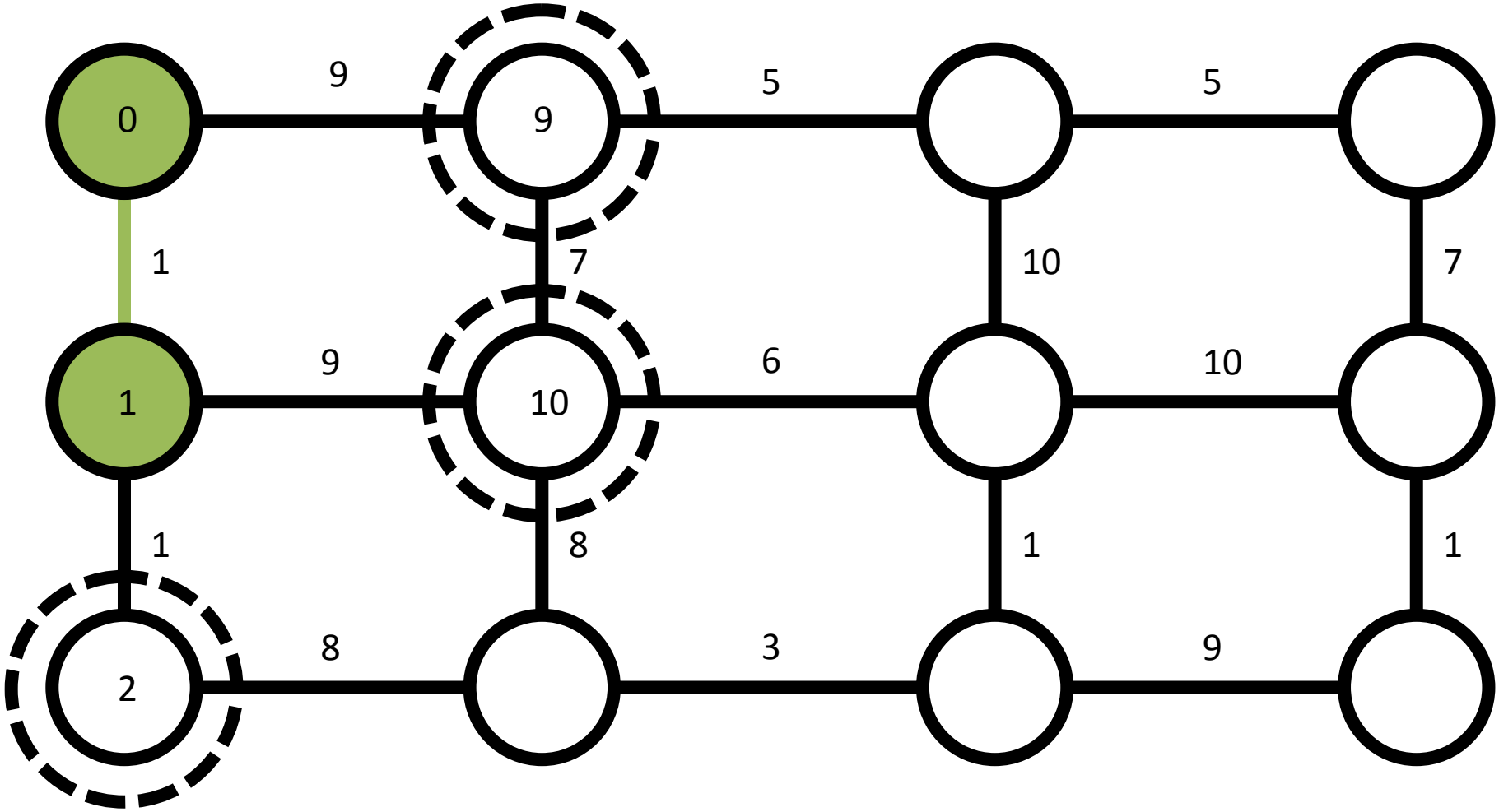

2
1
1
3
4
5

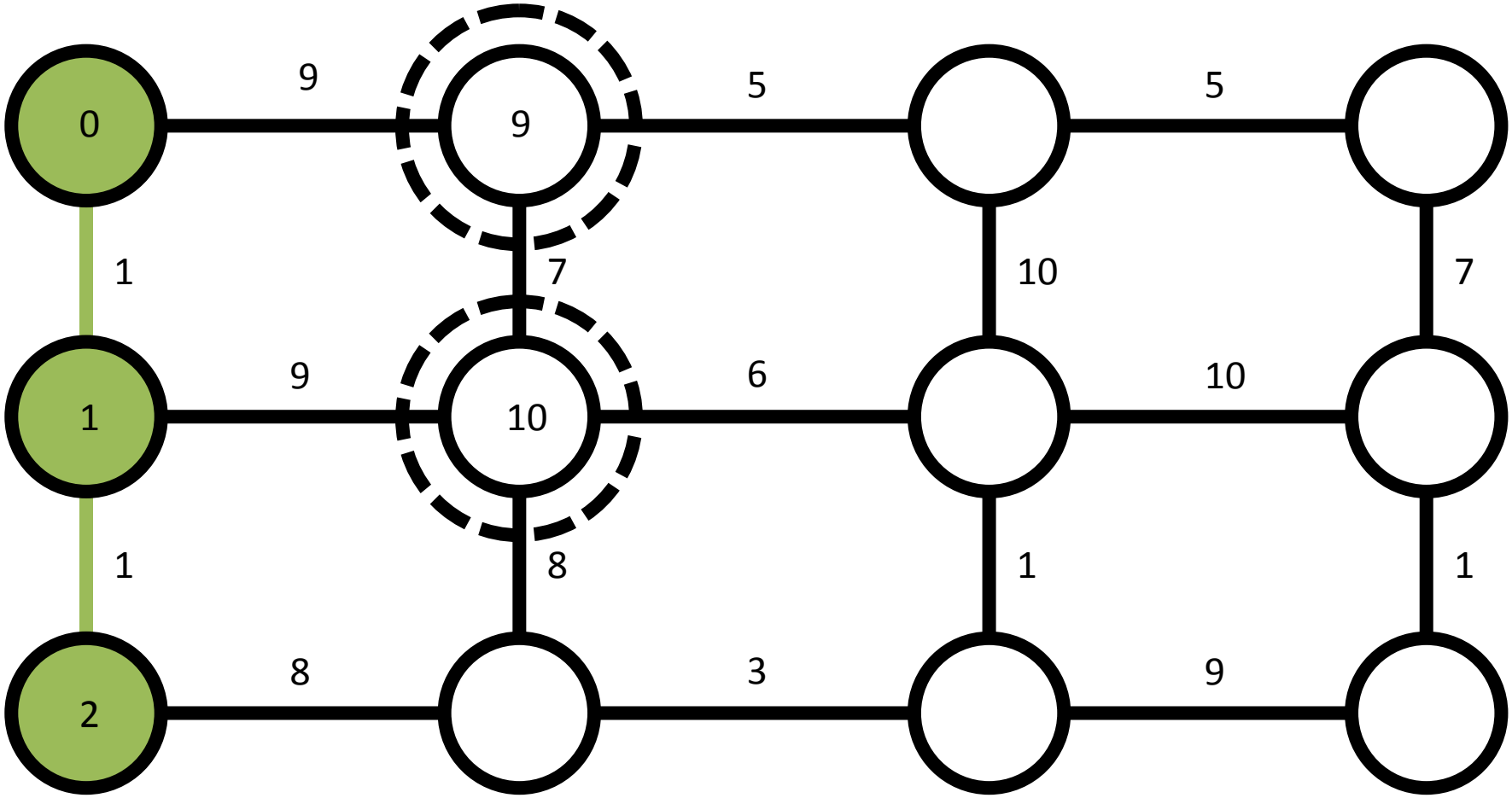
Dijkstra Algorithmus

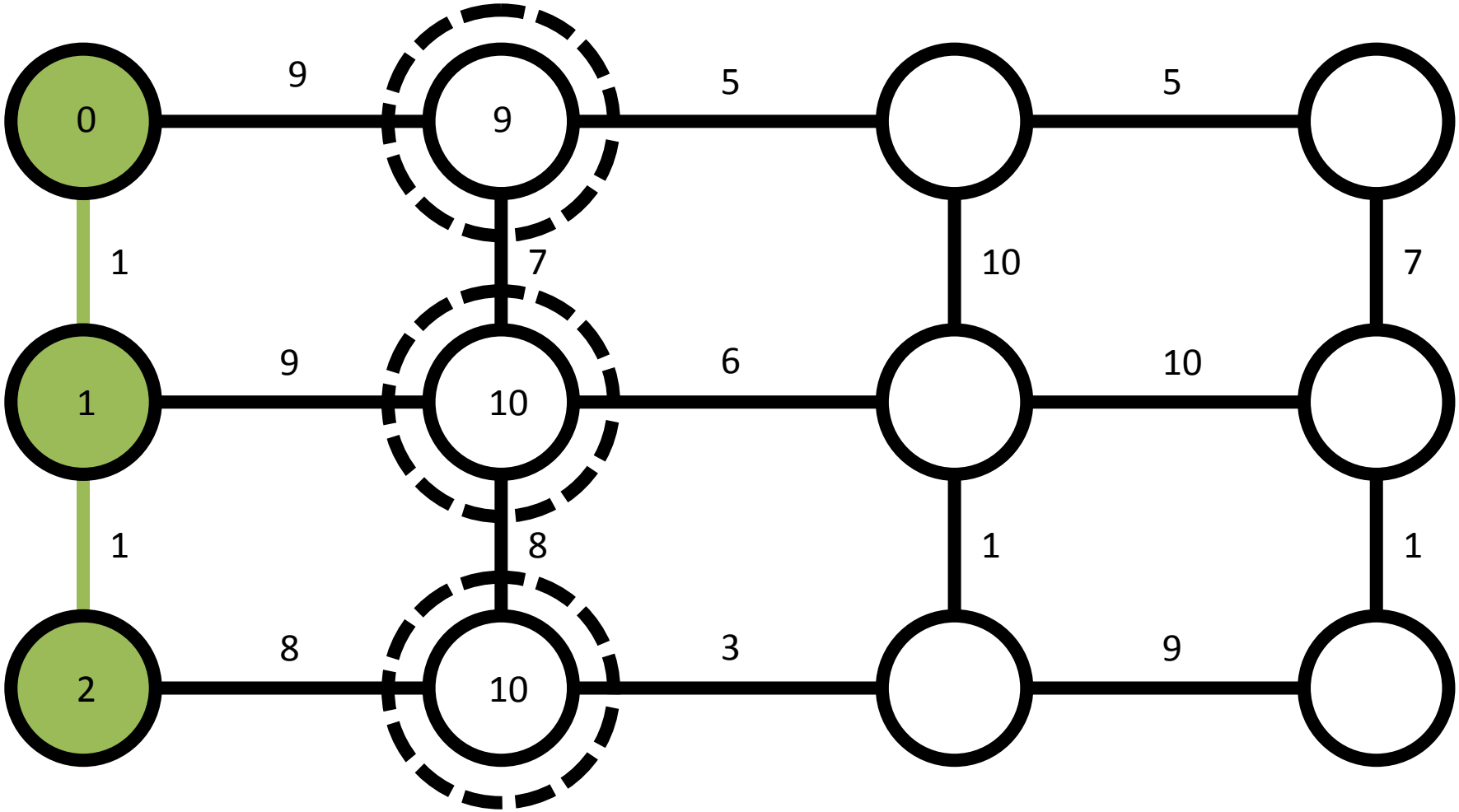

0
9
5
5
1
7
10
7
9
6
10
1
8
1
1
8
3
9

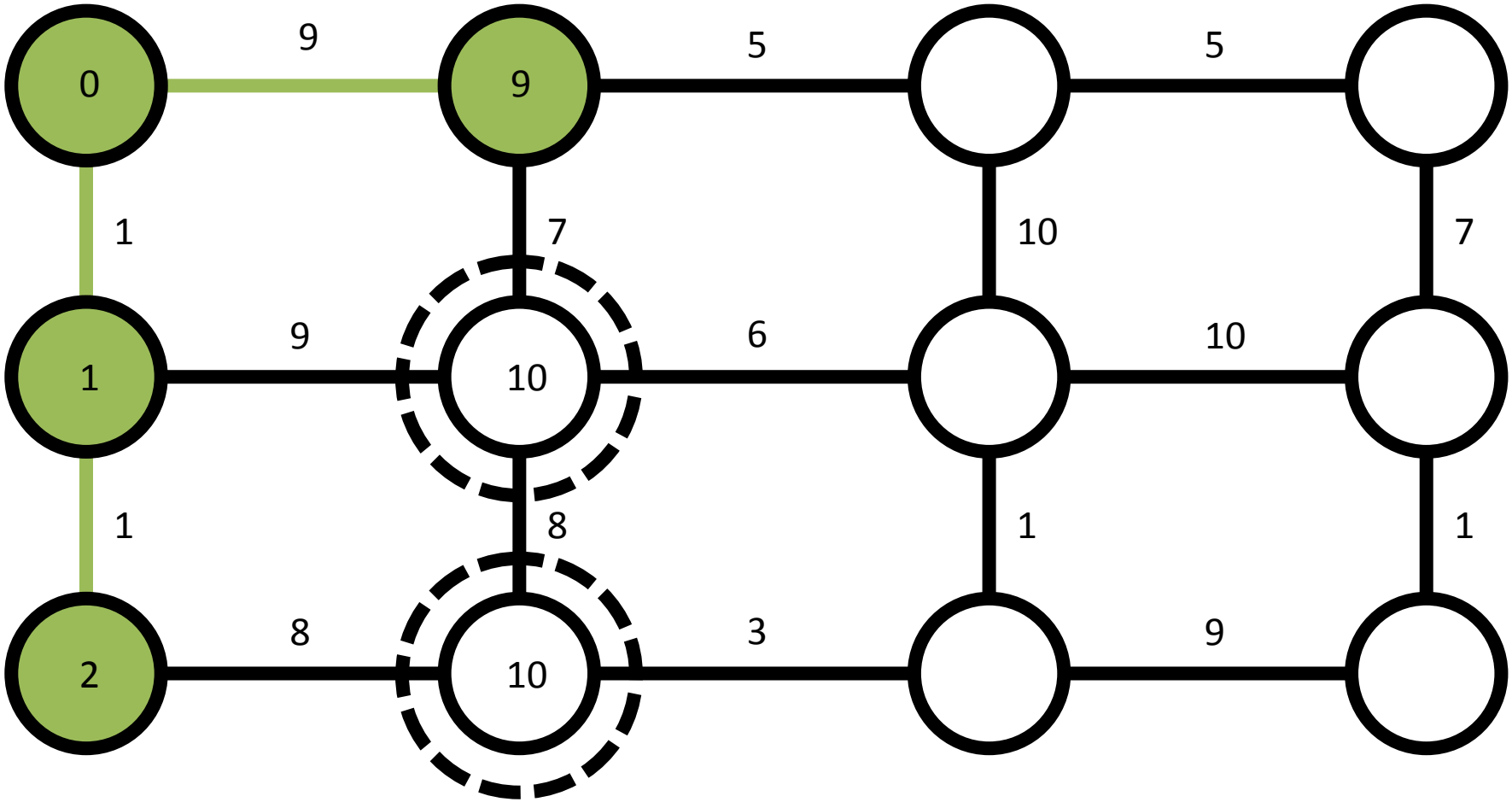

0
9
9
5
5
1
7
10
7
1
9
6
10
1
8
1
1
8
3
9

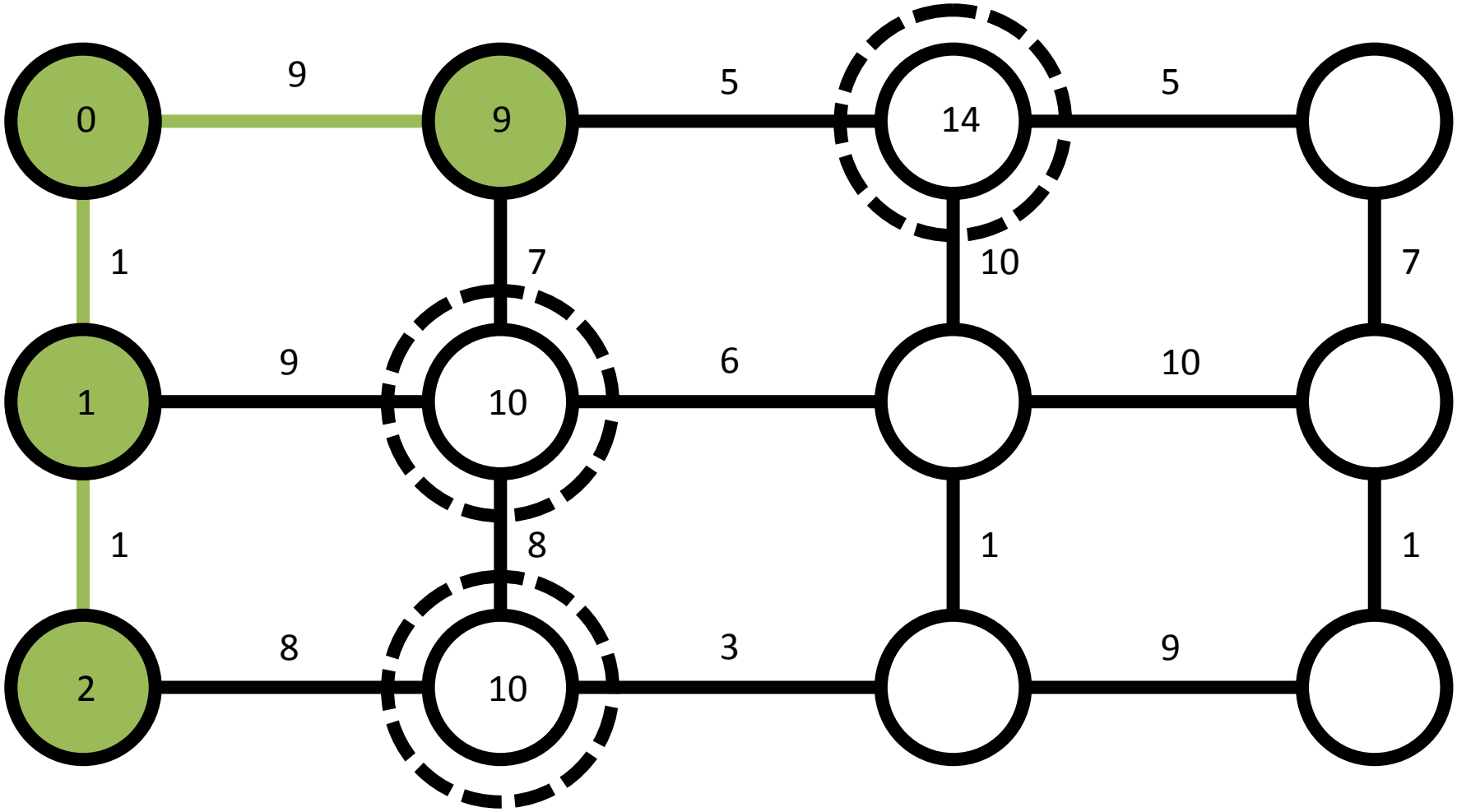

0
9
9
5
5
1
7
10
7
1
9
6
10
1
1
8
1
1
8
3
9

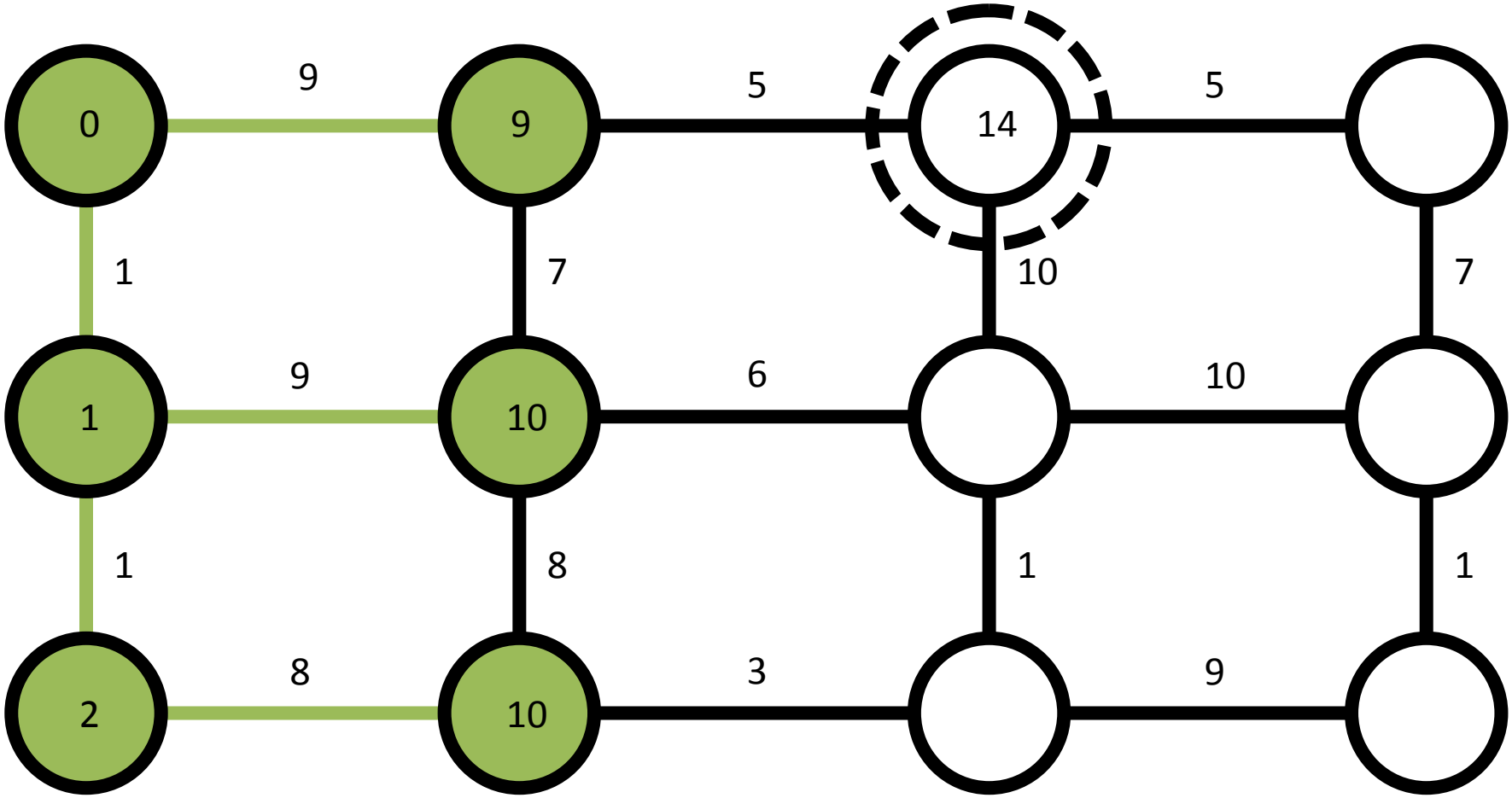

0
9
5
5
1
7
10
7
1
9
6
10
10
1
8
1
1
2
8
3
9

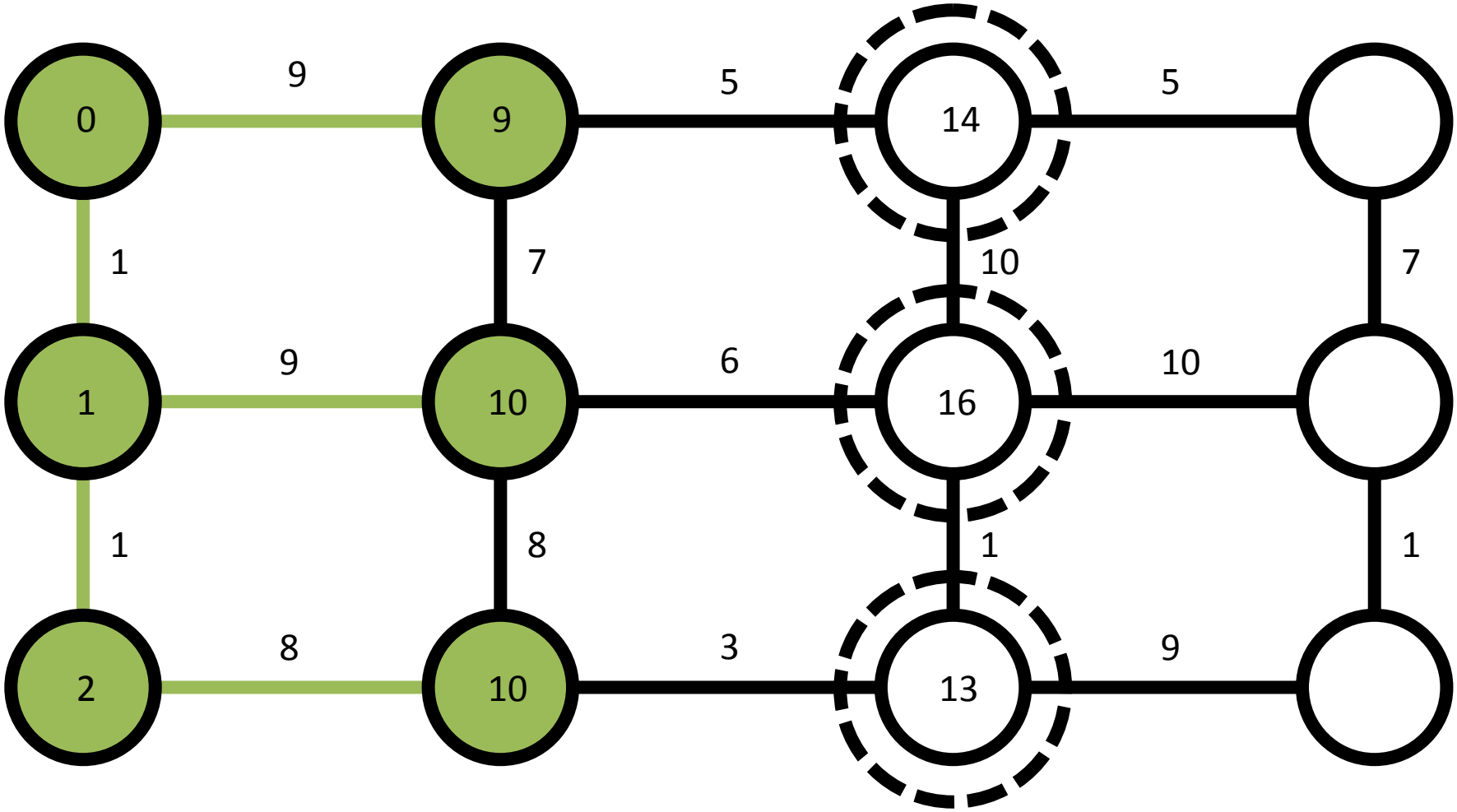

0
9
9
5
5
1
7
10
7
1
9
10
6
10
1
8
1
1
2
8
3
9

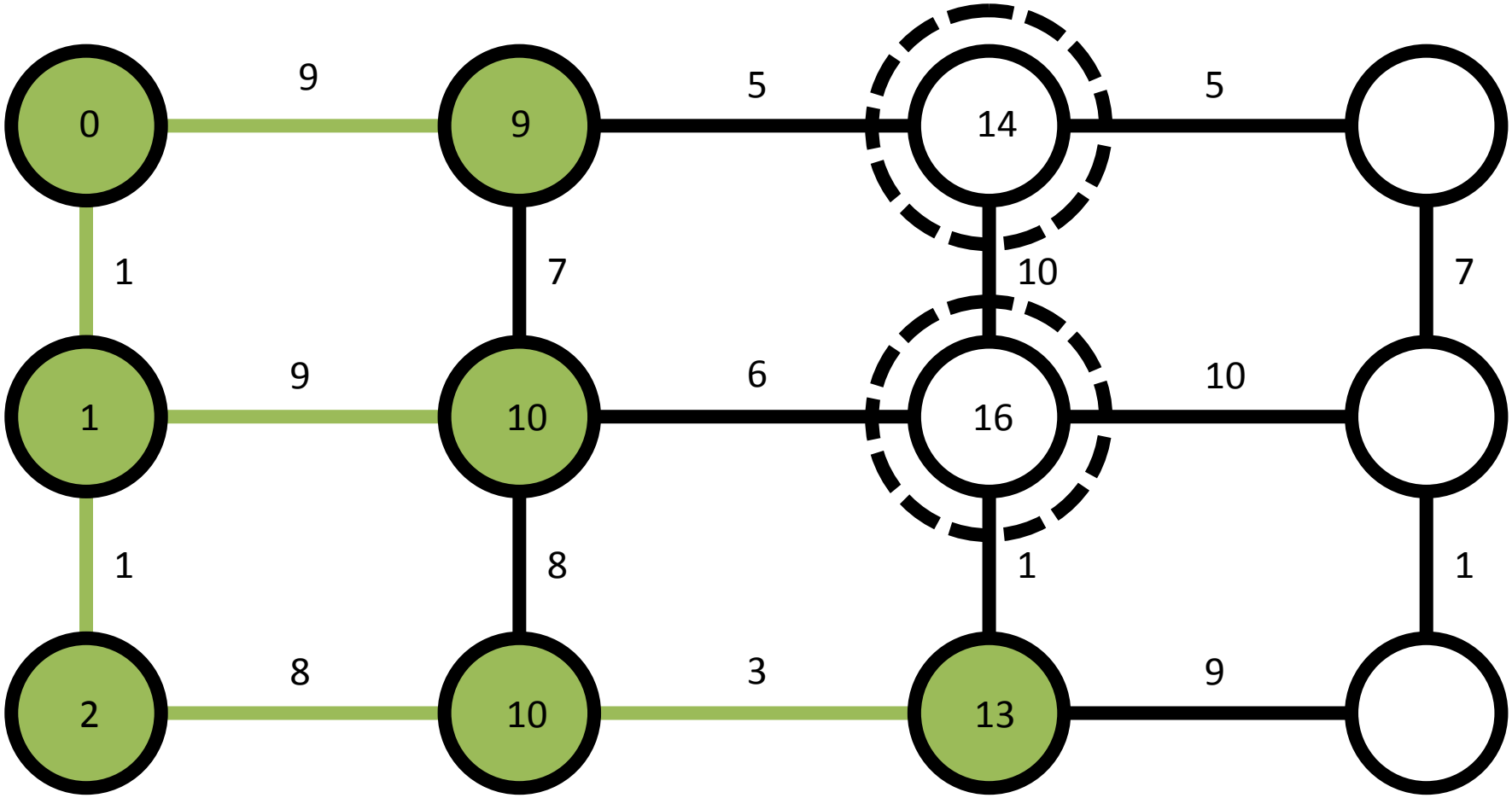

0
9
9
5
5
1
7
10
7
1
9
10
6
10
1
8
1
1
2
8
10
3
9

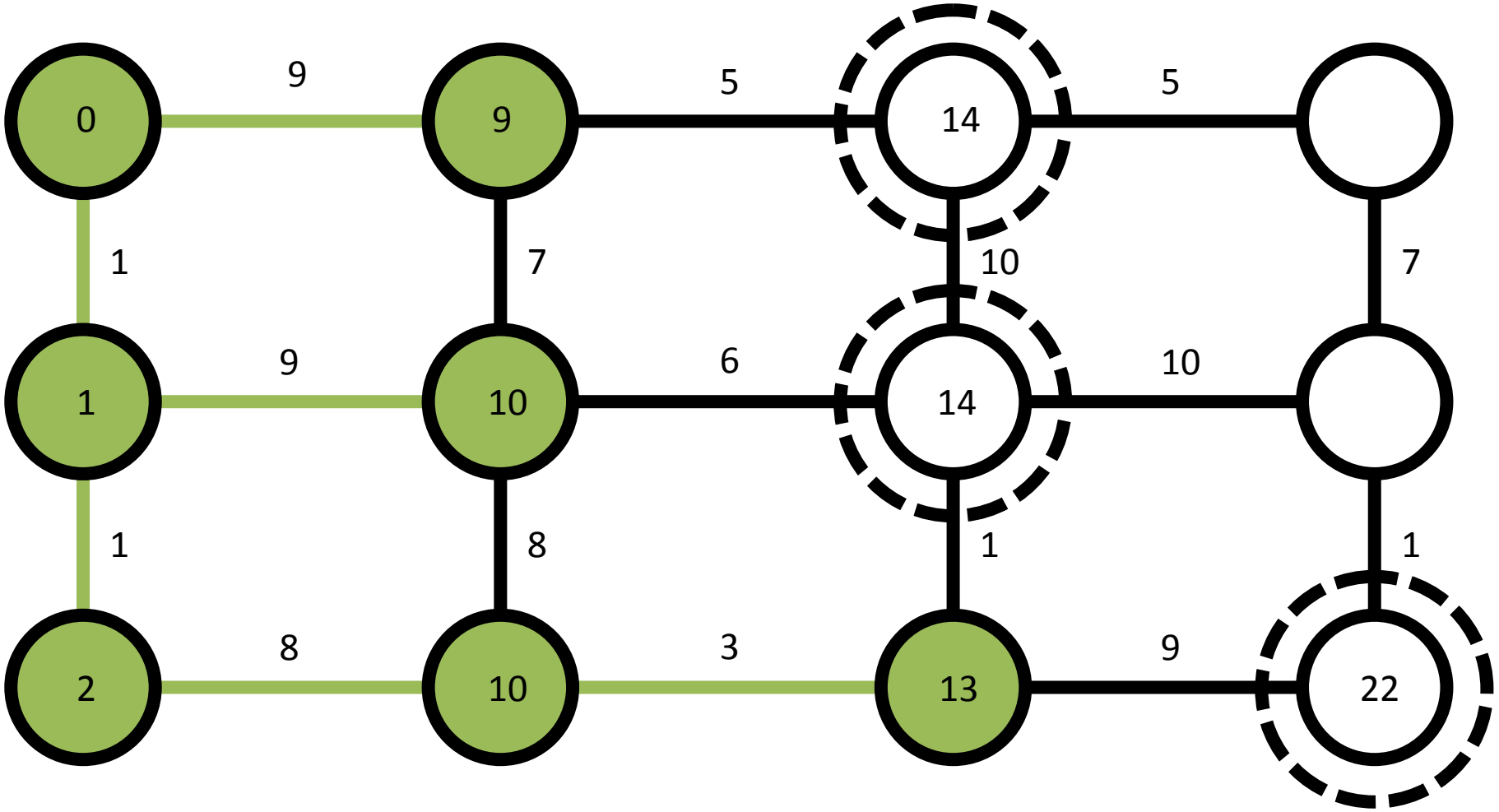

0
9
5
5
1
7
10
7
1
9
6
10
10
1
8
1
1
2
8
3
9
10
10

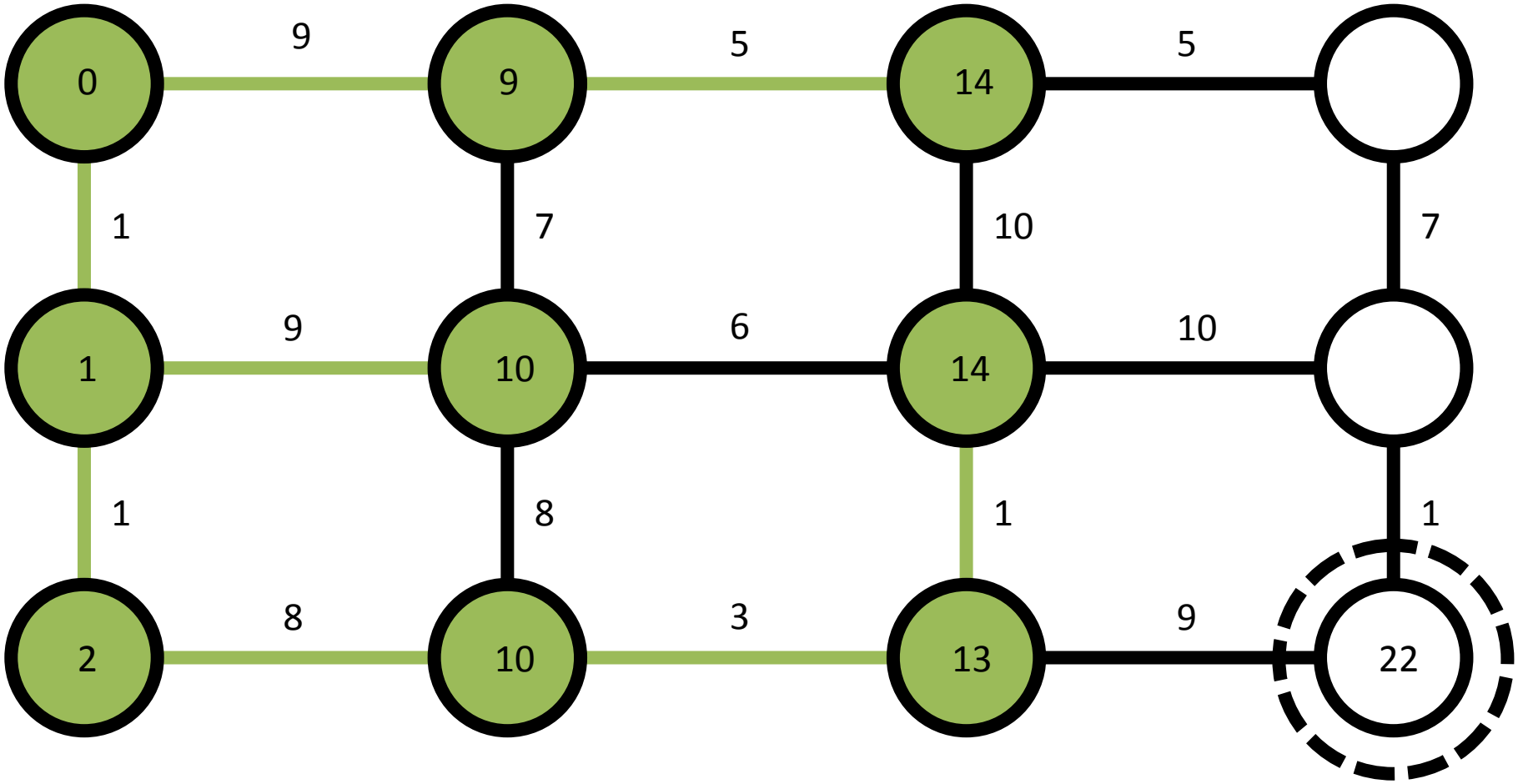

0
9
14
1
10
2
10
9
5
5
1
7
7
9
6
10
1
8
1
1
8
3
9

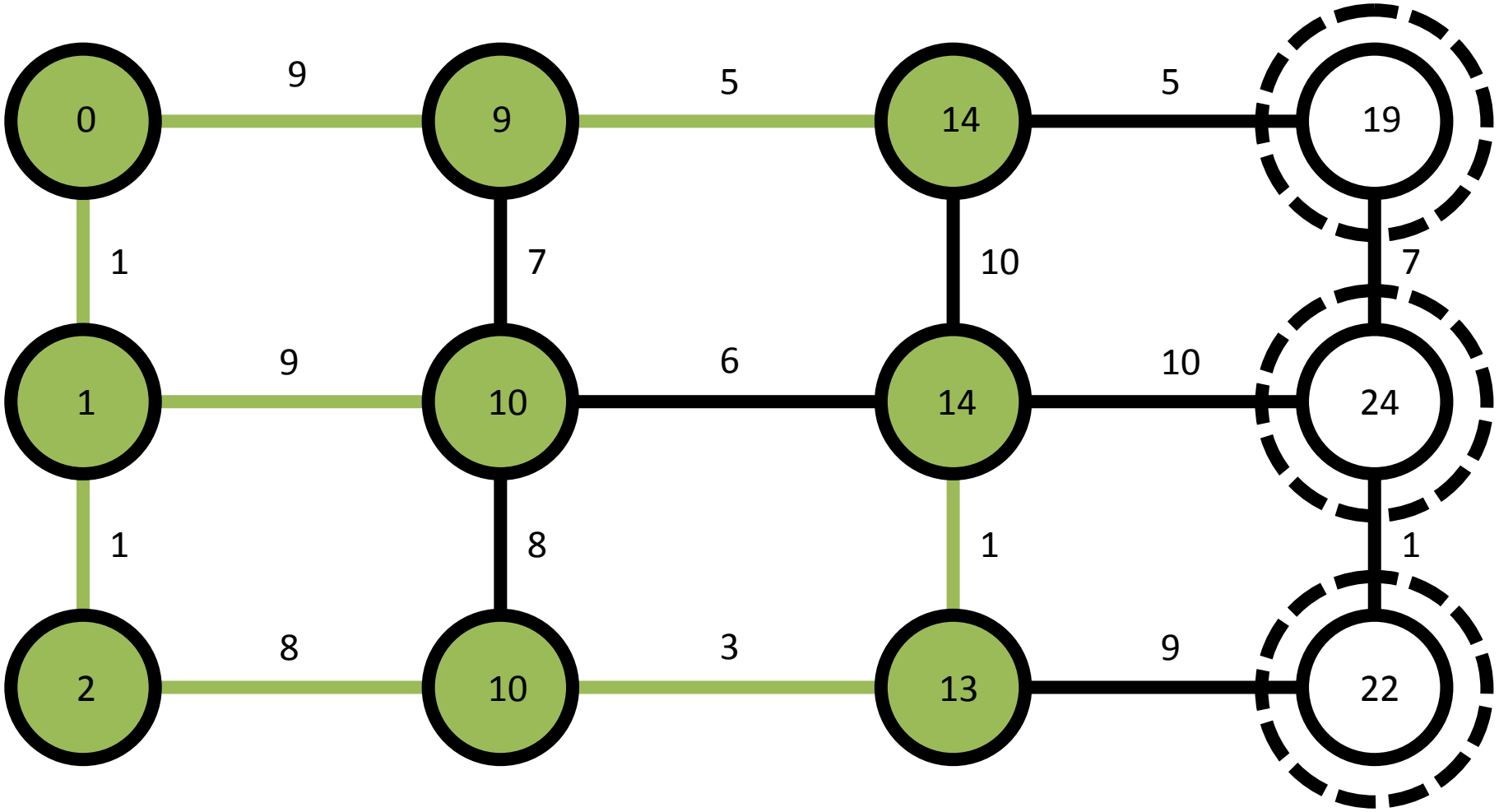

0
9
14
1
10
2
10
9
5
5
1
7
7
10
9
6
10
1
8
1
8
3
9

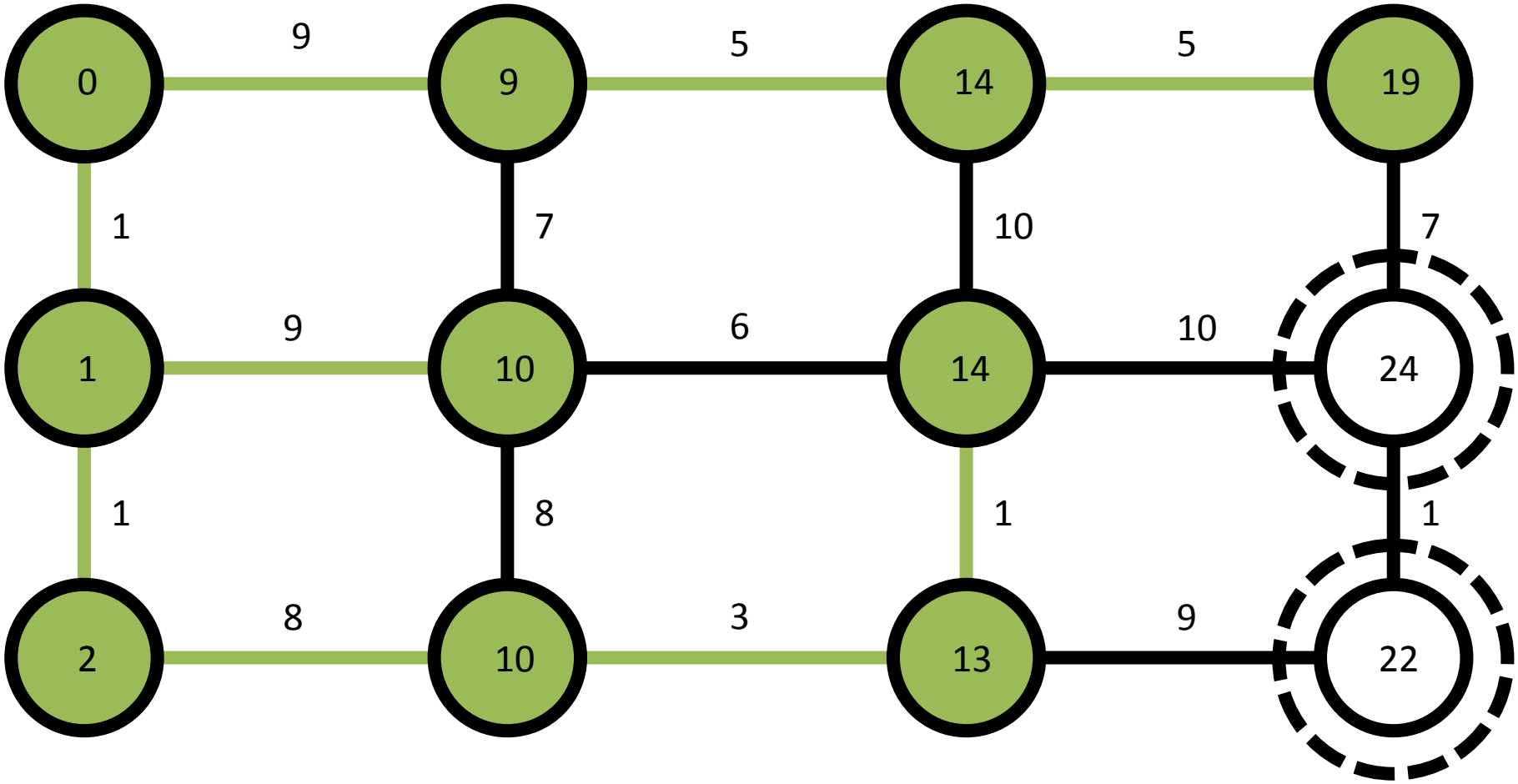

0
9
14
1
10
16
2
10
13
9
5
5
1
7
10
7
9
6
10
1
8
1
1
8
3
9

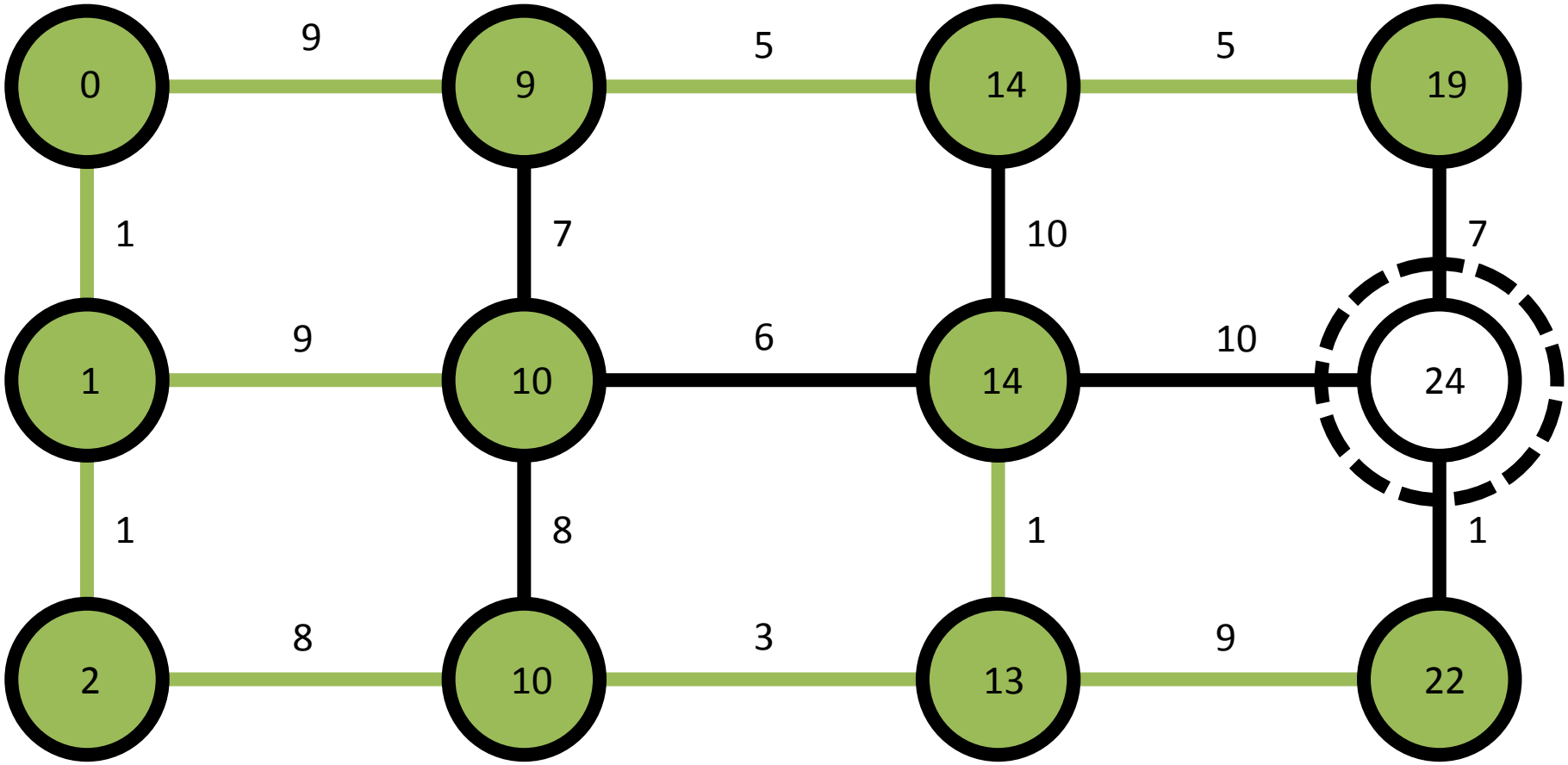

0
9
14
1
10
16
2
10
13
9
5
5
1
7
7
9
6
10
1
8
1
8
3
9

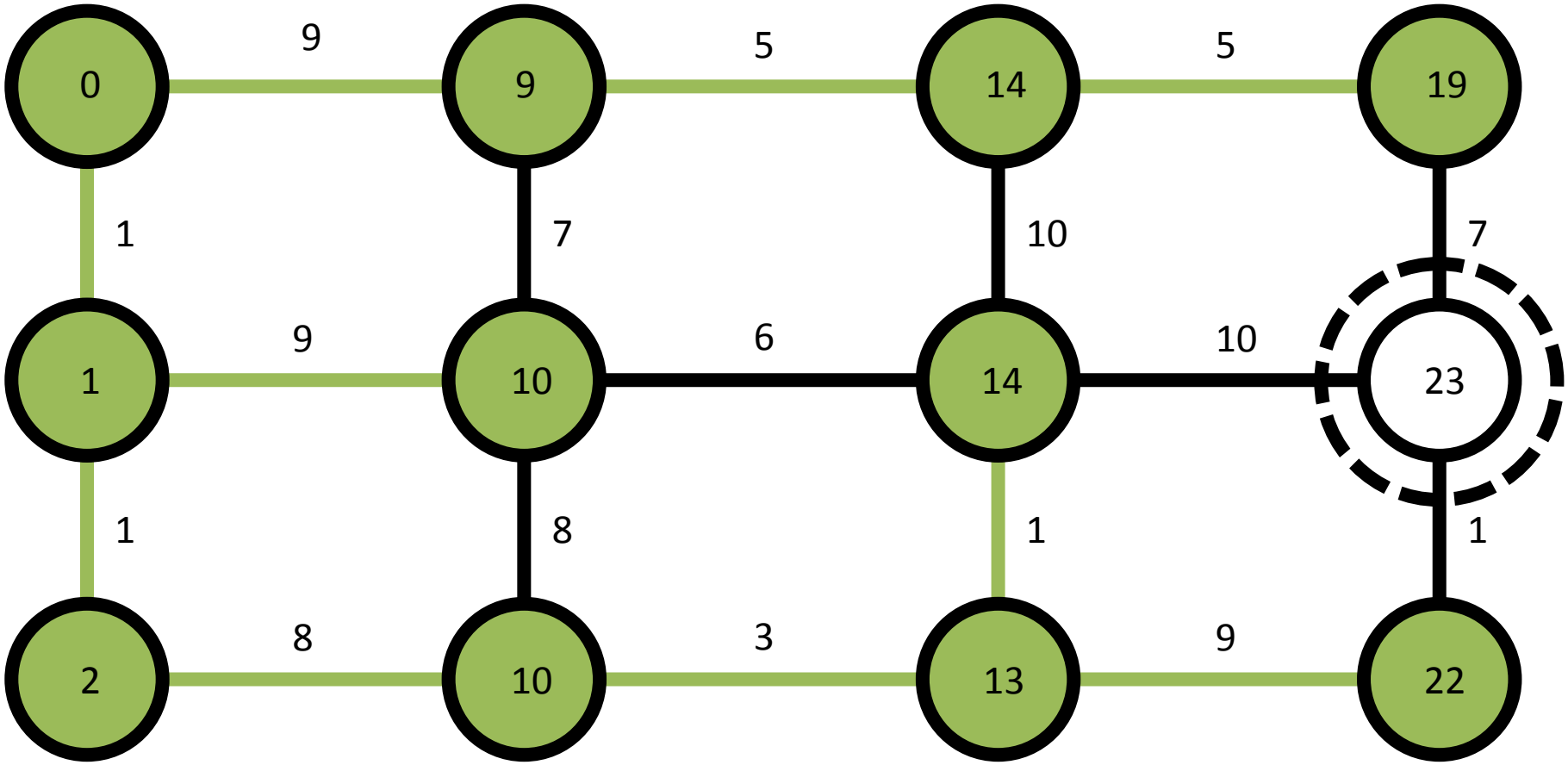

0
9
14
1
10
14
2
10
13
22
9
5
5
1
7
10
7
9
6
10
1
8
1
1
8
3
9

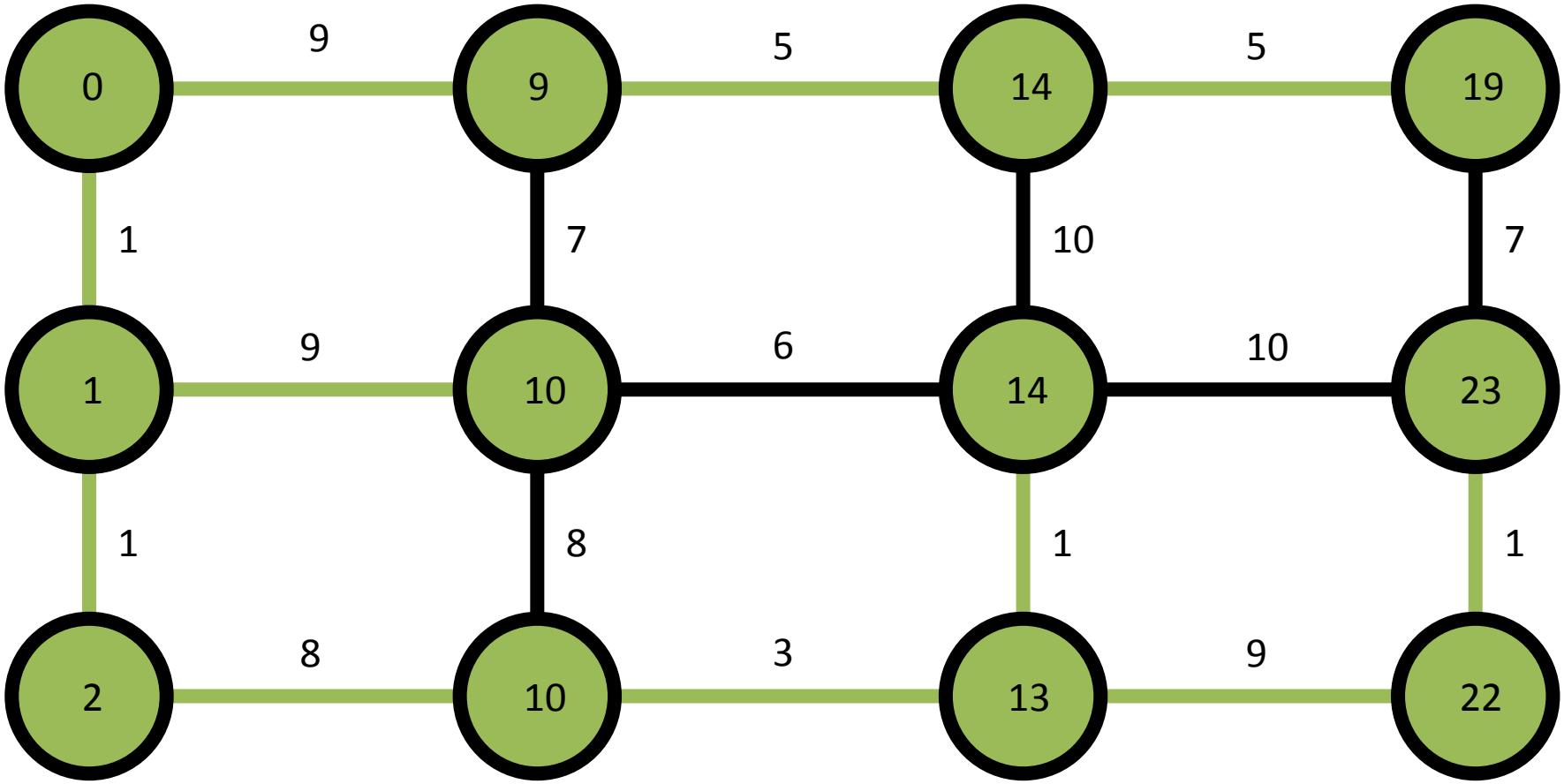

0
9
14
1
10
14
2
10
13
22
9
5
5
1
7
10
7
9
6
10
1
8
1
1
8
3
9


0
9
14
19
1
10
14
24
2
10
13
22
9
5
5
1
7
10
7
9
6
10
1
8
1
8
3
9


0
9
14
19
1
10
24
2
10
13
22
9
5
5
1
7
10
7
9
6
10
1
8
1
8
3
9

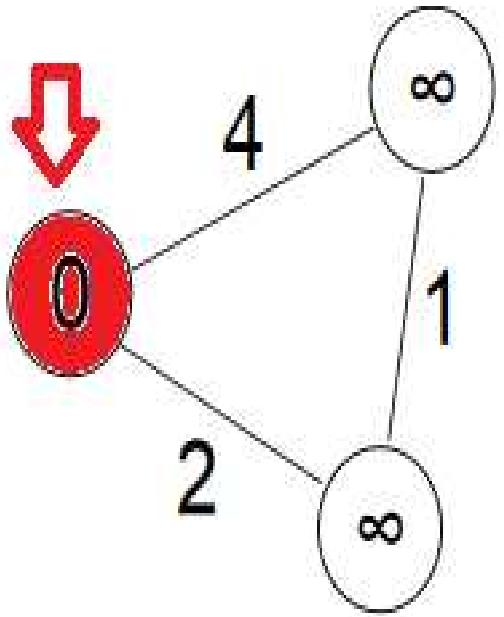

0
9
14
19
1
10
24
2
10
13
22
9
5
5
1
7
10
7
9
6
10
1
8
1
8
3
9


0
9
14
19
1
10
23
2
10
13
22
9
5
5
1
7
10
7
9
6
10
1
8
1
8
3
9

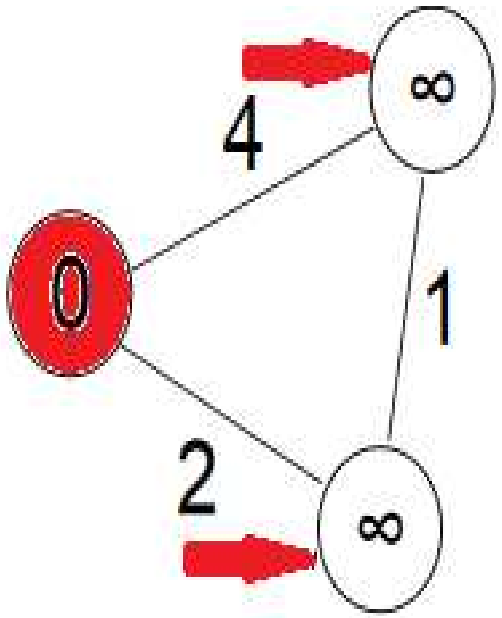

0
9
14
19
1
10
23
2
10
13
22
9
5
5
1
7
10
7
9
6
10
1
8
1
1
8
3
9

Implementierung in C++

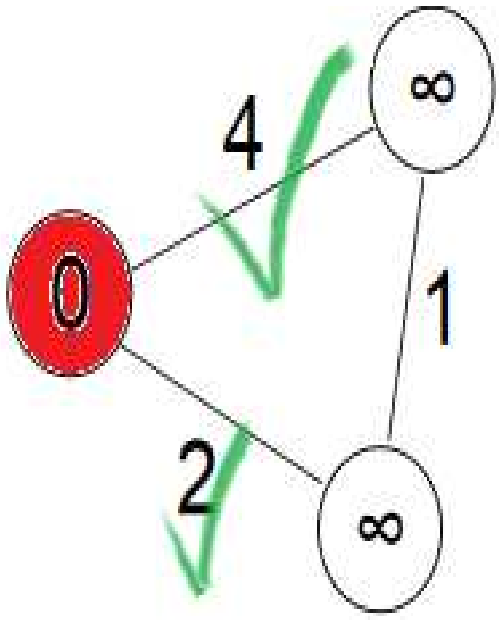
```
void Dijkstra(int node)
{
    Visited[node] = true;

    for(int i = 0; i < n; i++)
        if(!Visited[i] && AdjacencyMatrix[node][i] != 0)
            if(Distances[i] > Distances[node] + AdjacencyMatrix[node][i])
            {
                Distances[i] = Distances[node] + AdjacencyMatrix[node][i];
                prevNode[i] = node;
            }


    int min = INT_MAX;
    int index = -1;

    for(int i = 0; i < n; i++)
        if(!Visited[i] && Distances[i] < min)
        {
            index = i;
            min = Distances[i];
        }

    if(index != -1)
        Dijkstra(index);
}
```



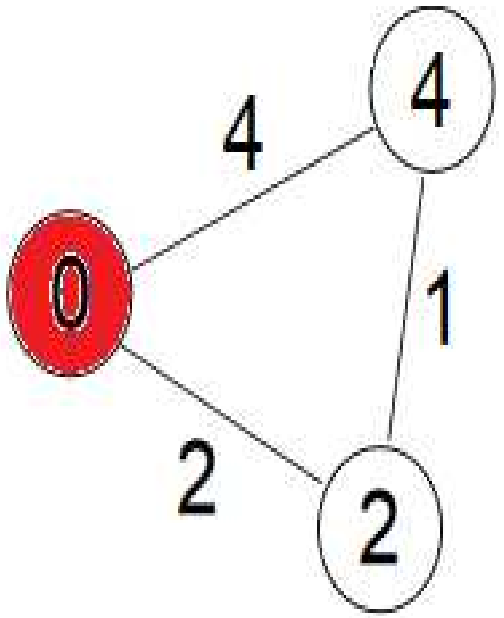
```
void Dijkstra(int node)
{
    Visited[node] = true;

    for(int i = 0; i < n; i++)
        if(!Visited[i] && AdjacencyMatrix[node][i] != 0)
            if(Distances[i] > Distances[node] + AdjacencyMatrix[node][i])
            {
                Distances[i] = Distances[node] + AdjacencyMatrix[node][i];
                prevNode[i] = node;
            }


    int min = INT_MAX;
    int index = -1;

    for(int i = 0; i < n; i++)
        if(!Visited[i] && Distances[i] < min)
        {
            index = i;
            min = Distances[i];
        }

    if(index != -1)
        Dijkstra(index);
}
```



```
void Dijkstra(int node)
{
    Visited[node] = true;

    for(int i = 0; i < n; i++)
        if(!Visited[i] && AdjacencyMatrix[node][i] != 0)
            if(Distances[i] > Distances[node] + AdjacencyMatrix[node][i])
            {
                Distances[i] = Distances[node] + AdjacencyMatrix[node][i];
                prevNode[i] = node;
            }


    int min = INT_MAX;
    int index = -1;

    for(int i = 0; i < n; i++)
        if(!Visited[i] && Distances[i] < min)
        {
            index = i;
            min = Distances[i];
        }

    if(index != -1)
        Dijkstra(index);
}
```

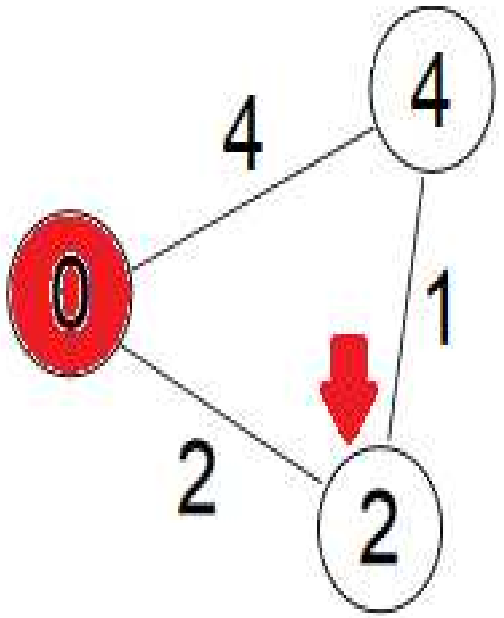


```
void Dijkstra(int node)
{
    Visited[node] = true;

    for(int i = 0; i < n; i++)
        if(!Visited[i] && AdjacencyMatrix[node][i] != 0)
            if(Distances[i] > Distances[node] + AdjacencyMatrix[node][i])
            {
                Distances[i] = Distances[node] + AdjacencyMatrix[node][i];
                prevNode[i] = node;
            }


    int min = INT_MAX;
    int index = -1;

    for(int i = 0; i < n; i++)
        if(!Visited[i] && Distances[i] < min)
        {
            index = i;
            min = Distances[i];
        }

    if(index != -1)
        Dijkstra(index);
}
```



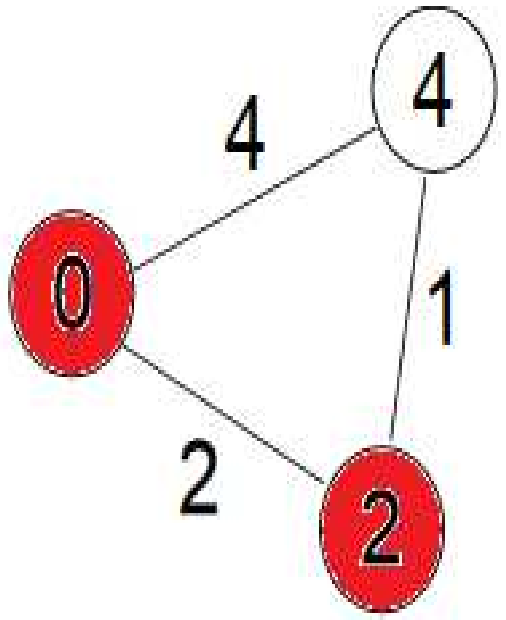
```
void Dijkstra(int node)
{
    Visited[node] = true;

    for(int i = 0; i < n; i++)
        if(!Visited[i] && AdjacencyMatrix[node][i] != 0)
            if(Distances[i] > Distances[node] + AdjacencyMatrix[node][i])
            {
                Distances[i] = Distances[node] + AdjacencyMatrix[node][i];
                prevNode[i] = node;
            }


    int min = INT_MAX;
    int index = -1;

    for(int i = 0; i < n; i++)
        if(!Visited[i] && Distances[i] < min)
        {
            index = i;
            min = Distances[i];
        }

    if(index != -1)
        Dijkstra(index);
}
```

```
void Dijkstra(int node)
{
    Visited[node] = true;

    for(int i = 0; i < n; i++)
        if(!Visited[i] && AdjacencyMatrix[node][i] != 0)
            if(Distances[i] > Distances[node] + AdjacencyMatrix[node][i])
            {
                Distances[i] = Distances[node] + AdjacencyMatrix[node][i];
                prevNode[i] = node;
            }


    int min = INT_MAX;
    int index = -1;

    for(int i = 0; i < n; i++)
        if(!Visited[i] && Distances[i] < min)
        {
            index = i;
            min = Distances[i];
        }

    if(index != -1)
        Dijkstra(index);
}
```

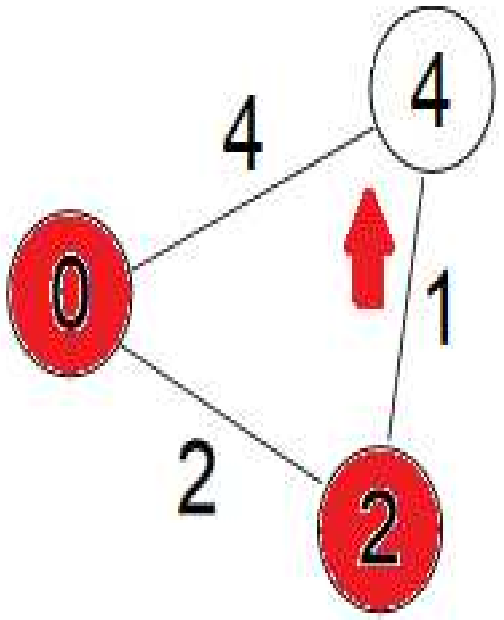


```
void Dijkstra(int node)
{
    Visited[node] = true;

    for(int i = 0; i < n; i++)
        if(!Visited[i] && AdjacencyMatrix[node][i] != 0)
            if(Distances[i] > Distances[node] + AdjacencyMatrix[node][i])
            {
                Distances[i] = Distances[node] + AdjacencyMatrix[node][i];
                prevNode[i] = node;
            }


    int min = INT_MAX;
    int index = -1;

    for(int i = 0; i < n; i++)
        if(!Visited[i] && Distances[i] < min)
        {
            index = i;
            min = Distances[i];
        }

    if(index != -1)
        Dijkstra(index);
}
```

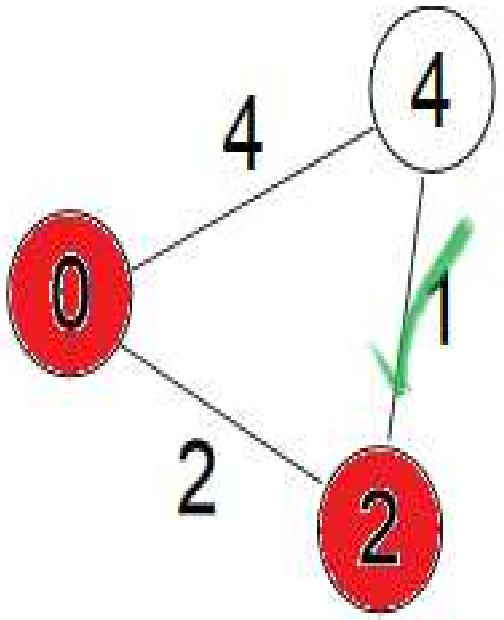
```
void Dijkstra(int node)
{
    Visited[node] = true;

    for(int i = 0; i < n; i++)
        if(!Visited[i] && AdjacencyMatrix[node][i] != 0)
            if(Distances[i] > Distances[node] + AdjacencyMatrix[node][i])
            {
                Distances[i] = Distances[node] + AdjacencyMatrix[node][i];
                prevNode[i] = node;
            }


    int min = INT_MAX;
    int index = -1;

    for(int i = 0; i < n; i++)
        if(!Visited[i] && Distances[i] < min)
        {
            index = i;
            min = Distances[i];
        }

    if(index != -1)
        Dijkstra(index);
}
```



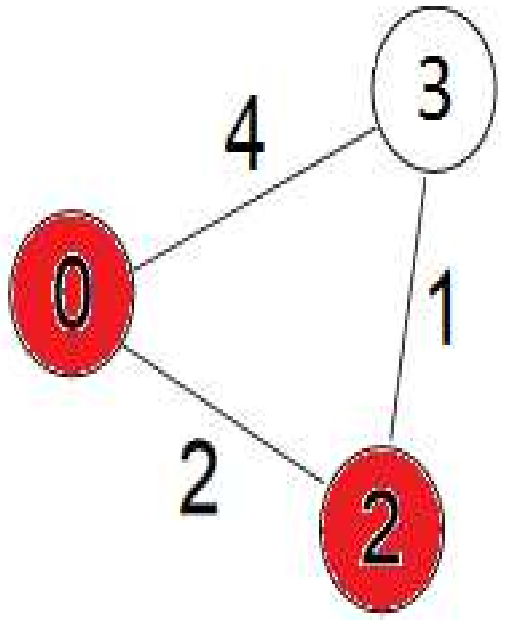
```
void Dijkstra(int node)
{
    Visited[node] = true;

    for(int i = 0; i < n; i++)
        if(!Visited[i] && AdjacencyMatrix[node][i] != 0)
            if(Distances[i] > Distances[node] + AdjacencyMatrix[node][i])
            {
                Distances[i] = Distances[node] + AdjacencyMatrix[node][i];
                prevNode[i] = node;
            }


    int min = INT_MAX;
    int index = -1;

    for(int i = 0; i < n; i++)
        if(!Visited[i] && Distances[i] < min)
        {
            index = i;
            min = Distances[i];
        }

    if(index != -1)
        Dijkstra(index);
}
```



```
void Dijkstra(int node)
{
    Visited[node] = true;

    for(int i = 0; i < n; i++)
        if(!Visited[i] && AdjacencyMatrix[node][i] != 0)
            if(Distances[i] > Distances[node] + AdjacencyMatrix[node][i])
            {
                Distances[i] = Distances[node] + AdjacencyMatrix[node][i];
                prevNode[i] = node;
            }


    int min = INT_MAX;
    int index = -1;

    for(int i = 0; i < n; i++)
        if(!Visited[i] && Distances[i] < min)
        {
            index = i;
            min = Distances[i];
        }

    if(index != -1)
        Dijkstra(index);
}
```

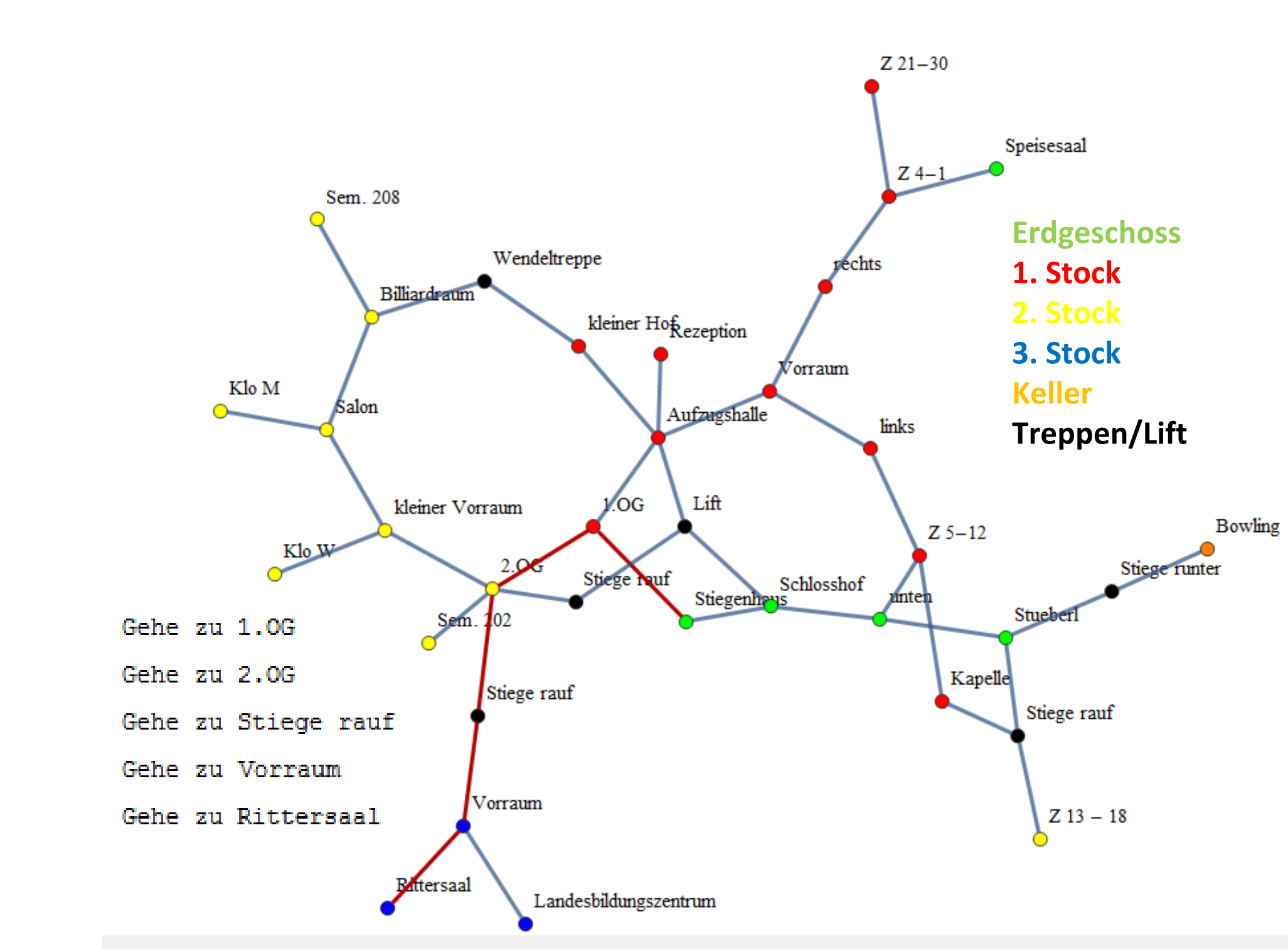


```
void Dijkstra(int node)
{
    Visited[node] = true;

    for(int i = 0; i < n; i++)
        if(!Visited[i] && AdjacencyMatrix[node][i] != 0)
            if(Distances[i] > Distances[node] + AdjacencyMatrix[node][i])
            {
                Distances[i] = Distances[node] + AdjacencyMatrix[node][i];
                prevNode[i] = node;
            }


    int min = INT_MAX;
    int index = -1;

    for(int i = 0; i < n; i++)
        if(!Visited[i] && Distances[i] < min)
        {
            index = i;
            min = Distances[i];
        }

    if(index != -1)
        Dijkstra(index);
}
```



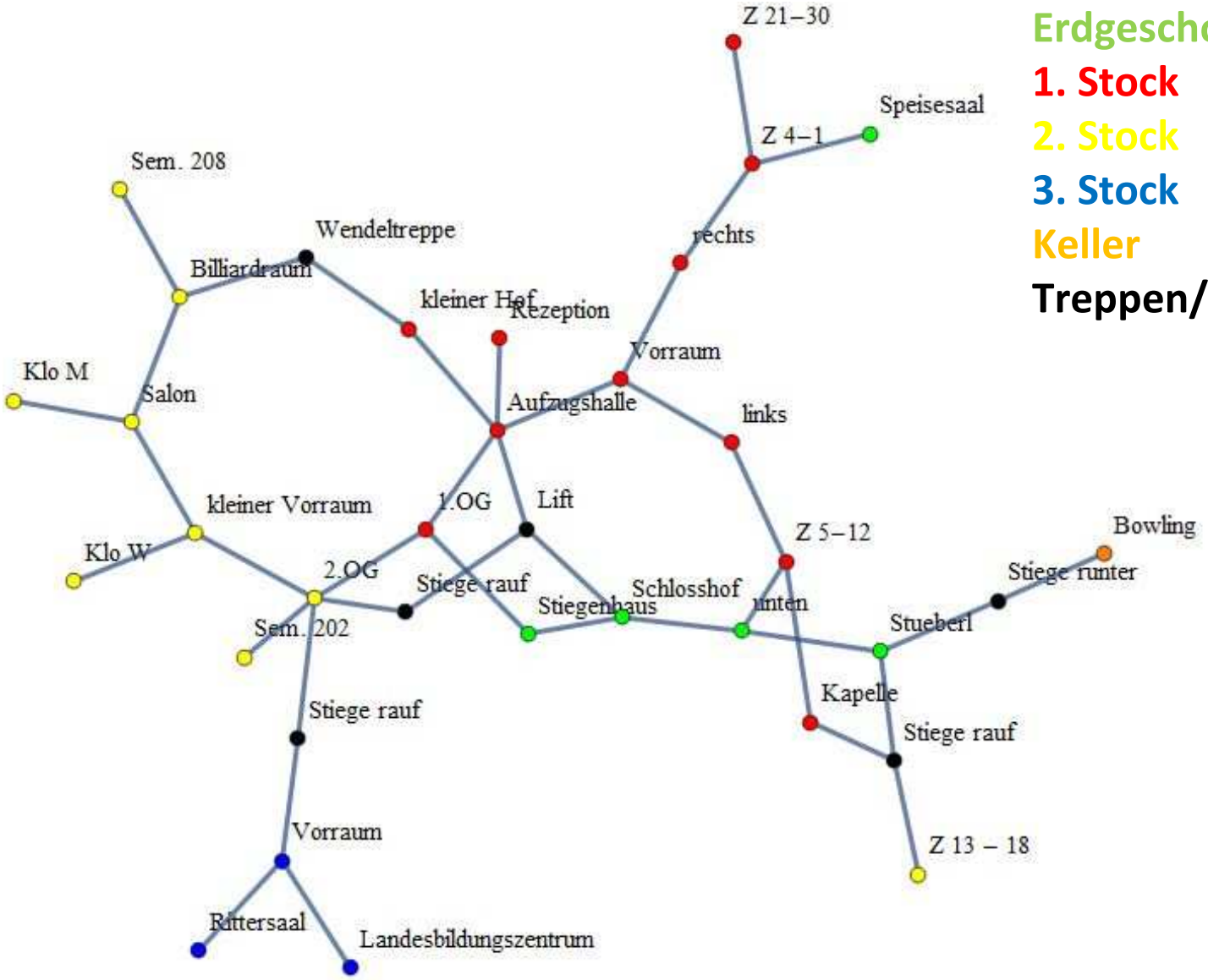
Implementierung in Mathematica

```
(*Speichert den gefundenen Wert in die fertige Liste*)

Actual[kand_] := {min = kand[[1]], value[[kand[[2]]]] = kand[[1]]}


(*Vereint die obigen Schritte in einer Funktion und gibt die fertige Liste aus*)

WholeStep[g_] := (mat = CreateMat[g]; defvalue[mat]; For[k = 1, k < length, k++, {SetPoint[mat, value]; Actual[kand];}])

(*speichert die Punkte die man entlanggehen muss um zum Punkt p zu kommen in eine Liste und die begangenen Wege in eine Liste*)
Way[g_, p_] := (WholeStep[g]; specway = {p}; For[i = 1, specway[[i]] ≠ 1, i++, AppendTo[specway, way[[(specway[[i]])]]]]; specway = Reverse[specway]; elist = {};
  For[i = 1, specway[[i]] ≠ p, i++, AppendTo[elist, specway[[i]] ↔ specway[[i + 1]]]])

(*Erzeugt eine Wegbeschreibung mit Karte zum gewünschten Punkt*)
(*Wegbeschreibung2[g_,p_,start_]:=(Way[g,p,start];For[i=2,specway[[i]]≠p,i++,Print["Go to Point ",specway[[i]]];Print["Go to Point ",p];HighlightGraph[g,elist])*)

Wegbeschreibung[g_, p_] := (Way[g, p]; For[i = 2, specway[[i]] ≠ p, i++, Print["Go to Point ", specway[[i]]]; Print["Go to Point ", p]; HighlightGraph[g, elist])

WegbeschreibungS[g_, p_] := (Way[g, p]; For[i = 2, specway[[i]] ≠ p, i++, Print["Gehe zu ", PropertyValue[{g, specway[[i]]}, VertexLabels]]];
  Print["Gehe zu ", PropertyValue[{g, p}, VertexLabels]]; HighlightGraph[g, elist])

WegbeschreibungSchloss[punkt_] := Magnify[WegbeschreibungS[schloss, (Flatten[Position[labelsonly, punkt]][[1]])], 1.5]

WegbeschreibungSchloss2[punkt_, position_] := WegbeschreibungS[schloss, (Flatten[Position[labelsonly, punkt]][[position]])]
```


Z 21–30
Speisesaal
Z 4–1
Sem. 208
Wendeltreppe
rechts
Billiardraum
kleiner Hof
Rezeption
Vorraum
Klo M
Salon
Aufzugshalle
links
kleiner Vorraum
1.OG
Lift
Z 5–12
Bowling
Klo W
2.OG
Stiege runter
Stiege rauf
Schlosshof
Stiegenhaus
unten
Sem. 202
Stueberl
Kapelle
Stiege rauf
Stiege rauf
Z 13 – 18
Vorraum
Rittersaal
Landesbildungszentrum
Erdgeschoss
1. Stock
2. Stock
3. Stock
Keller
Treppen/Lift
Gehe zu 1.OG
Gehe zu 2.OG
Gehe zu Stiege rauf
Gehe zu Vorraum
Gehe zu Rittersaal

Das Schloss als Graph

Schloss als Graph



Erdgeschoss

1. Stock

2. Stock

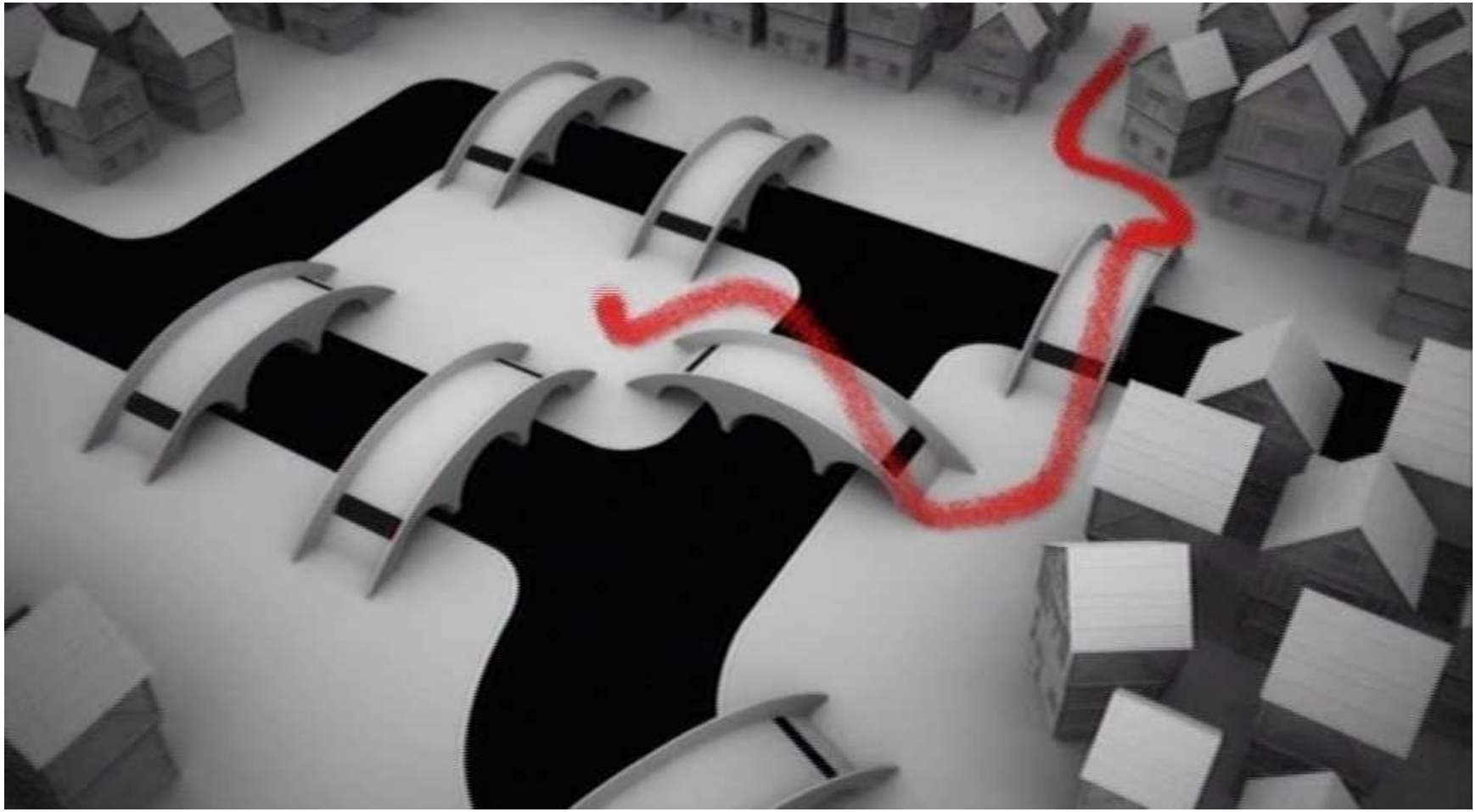
3. Stock

Keller

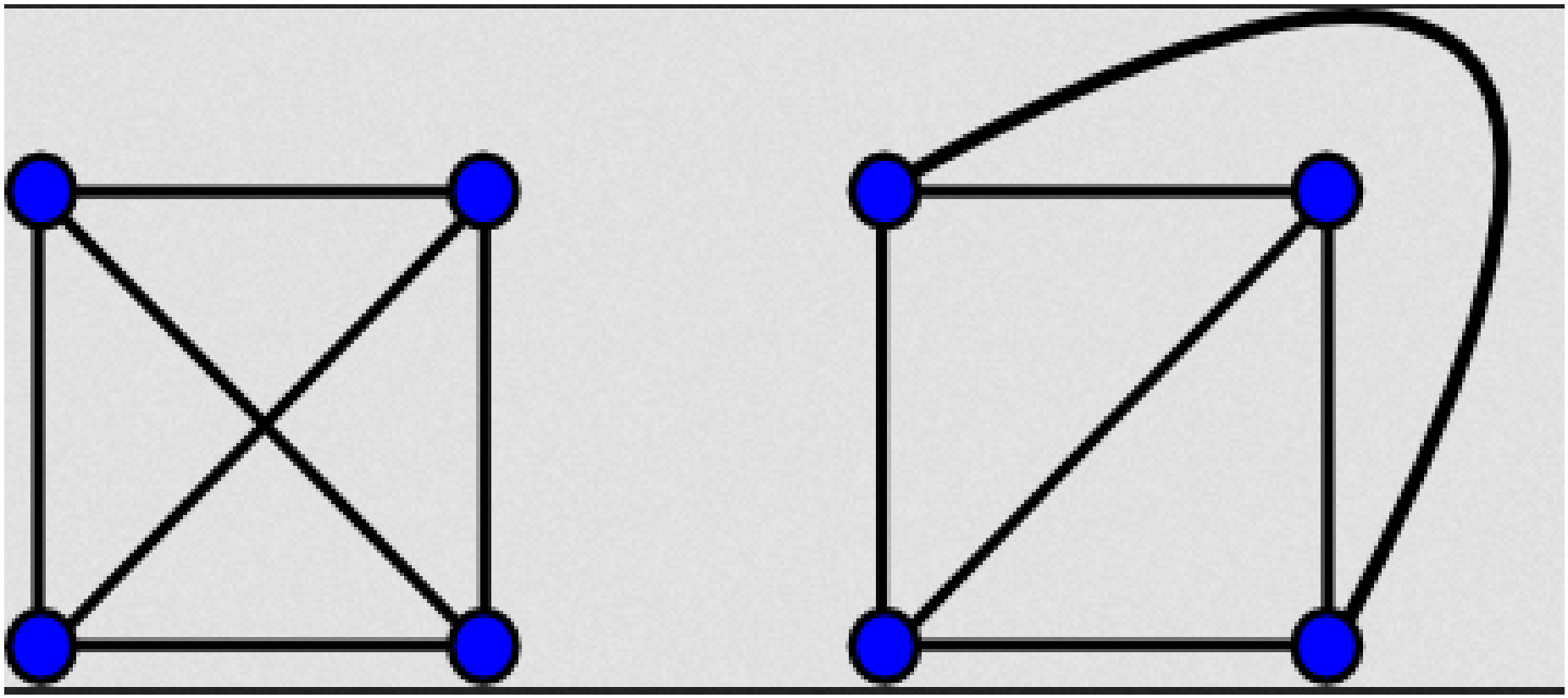
Treppen/Lift

Die Brücken von Königsberg

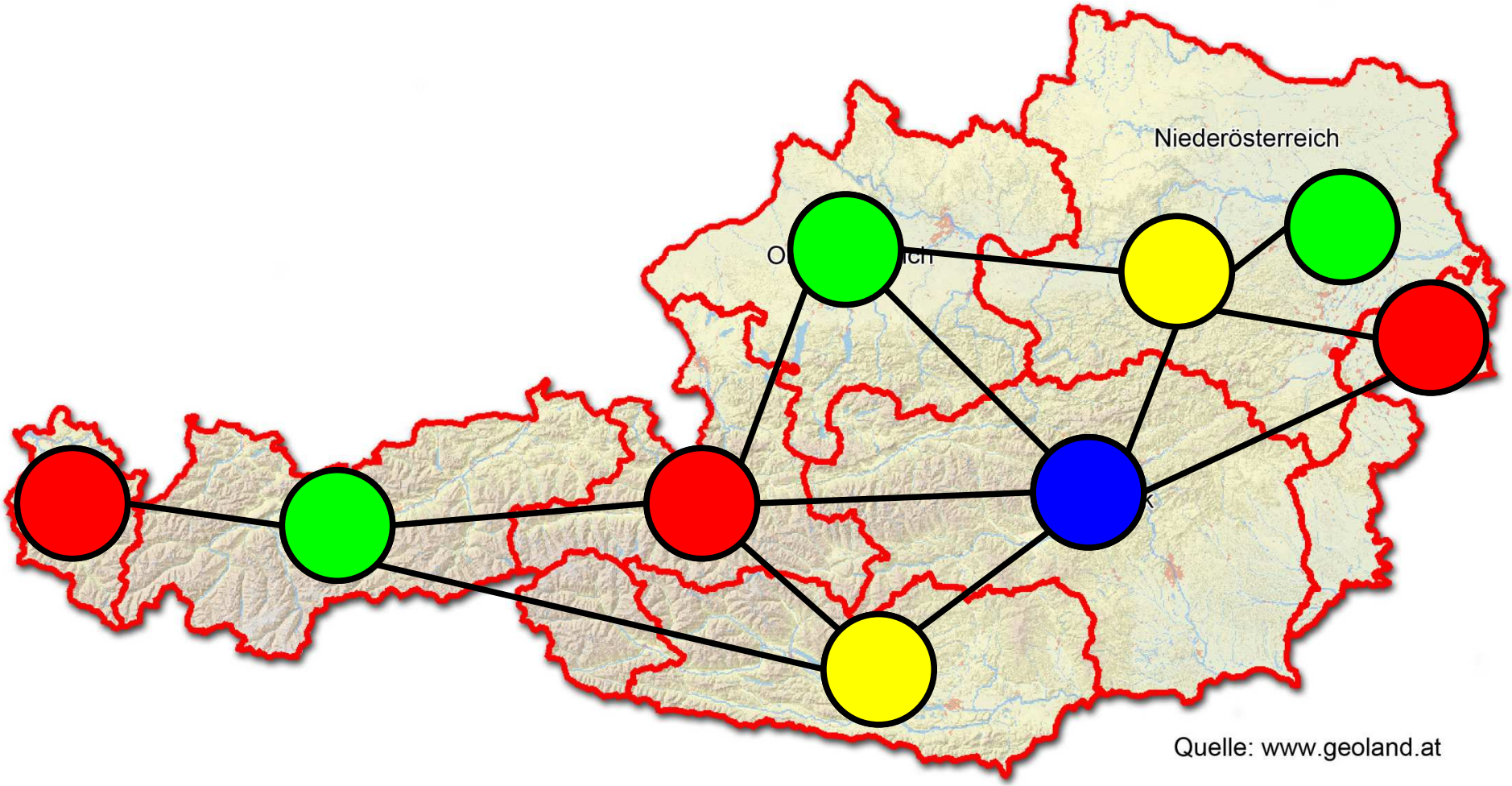
Brücken von Königsberg

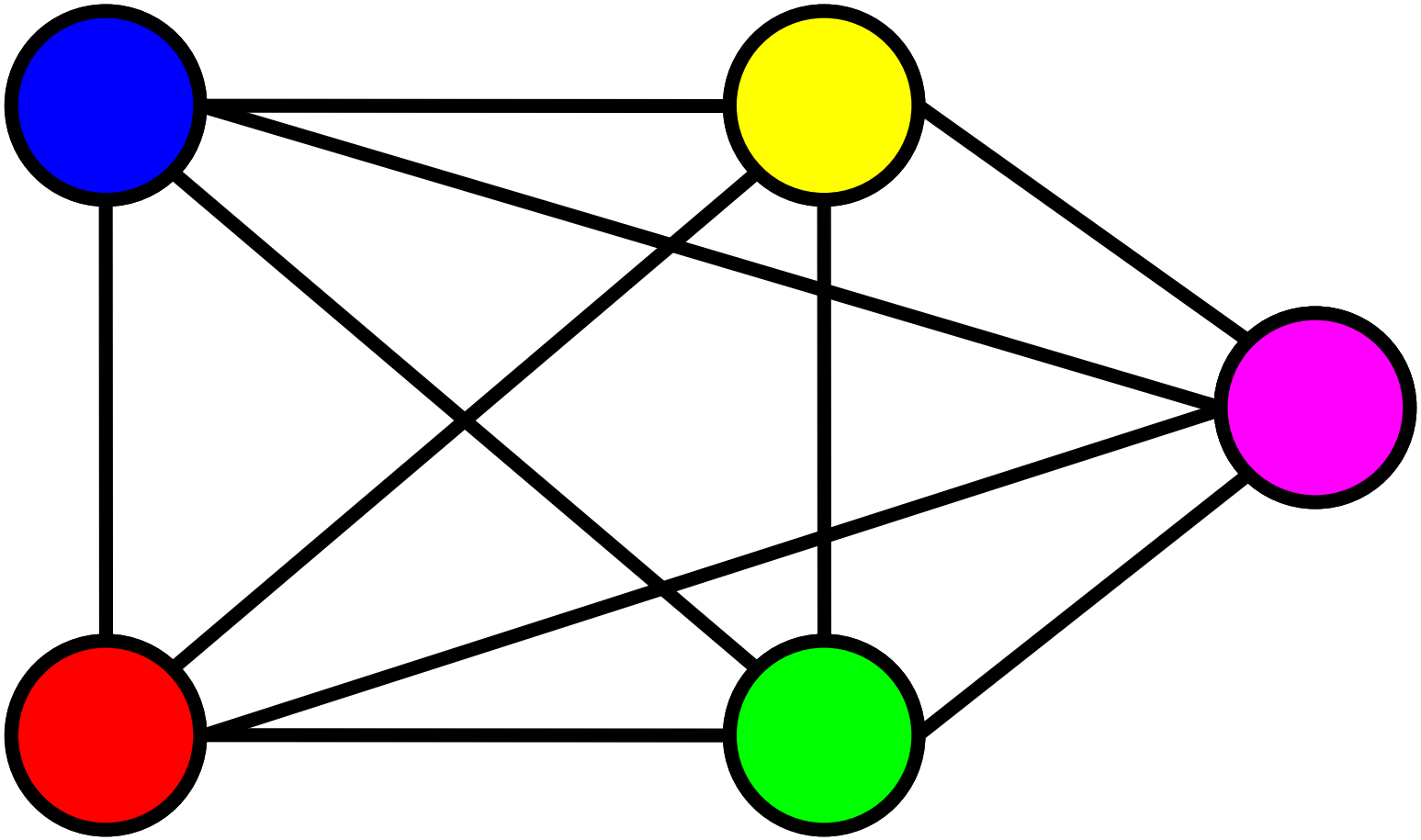


Planare Graphen



Knotenfärbung


Niederösterreich
Quelle: www.geoland.at



Was nehmen wir mit?

- Graphen
- Karten → Graphen darstellen
- kürzesten Weg
- Prinzip von Navigationssystemen
- Arbeiten mit Mathematica
- Dijkstra Algorithmus
- Implementierung in Programmiersprachen

Vielen Dank für eure Aufmerksamkeit!